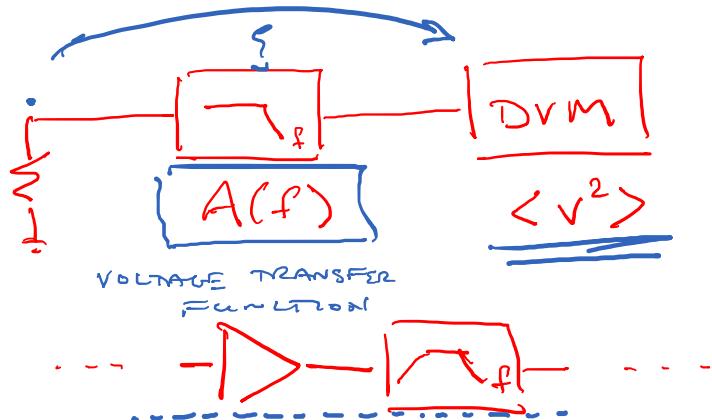


NOISE BANDWIDTH REVISITED

$$S_v = 4k_B T R$$

$$\underline{R @ T}$$



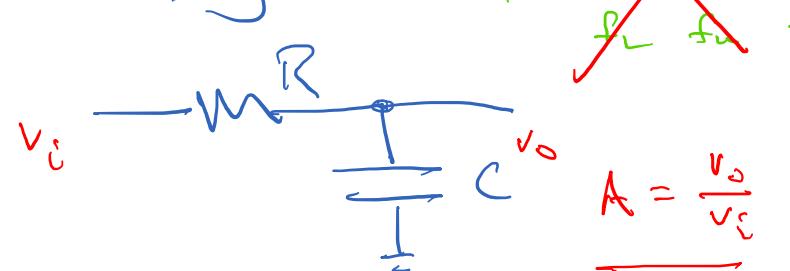
NOISE BANDWIDTH:

$$\Rightarrow \Delta f_N = \int |A(f)|^2 df$$

$$\underline{\langle v^2 \rangle} = 4k_B T R \Delta f_N$$

"BRICK WALL" FILTER

e.g.



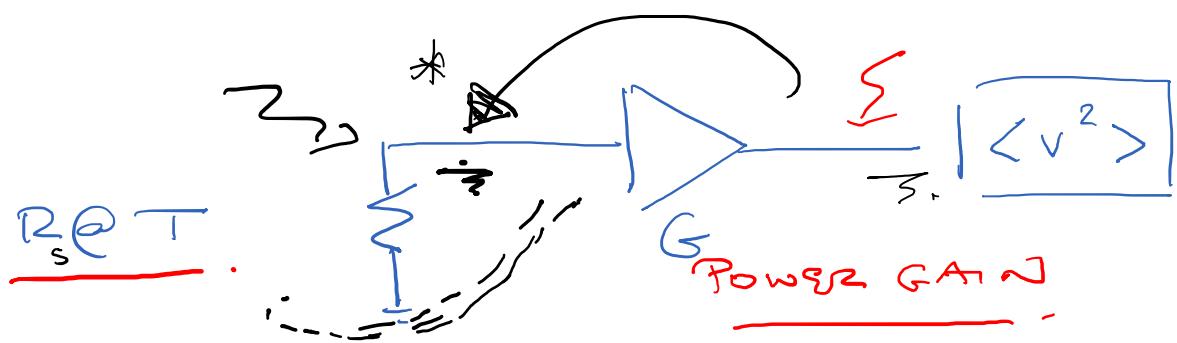
$$\tau = RC$$

$$\rightarrow \Delta f_N = \frac{1}{4RC}$$

(compare:

$$\Delta f_{3dB} = \frac{1}{2\pi RC}$$

AMPLIFIER ADDS NOISE



δ_x, δ_y

TOTAL FLUCTUATION

$$[\delta_x^2 + \delta_y^2]^{1/2}$$

$$\delta_z^2 = \delta_x^2 + \delta_y^2$$

ADDITIVE NOISE
INCONSEQUENTLY

OUTPUT : $\overline{v^2} = G \left[4k_b T_s \Delta f_N \right]$ ←
+ NOISE [Amp].

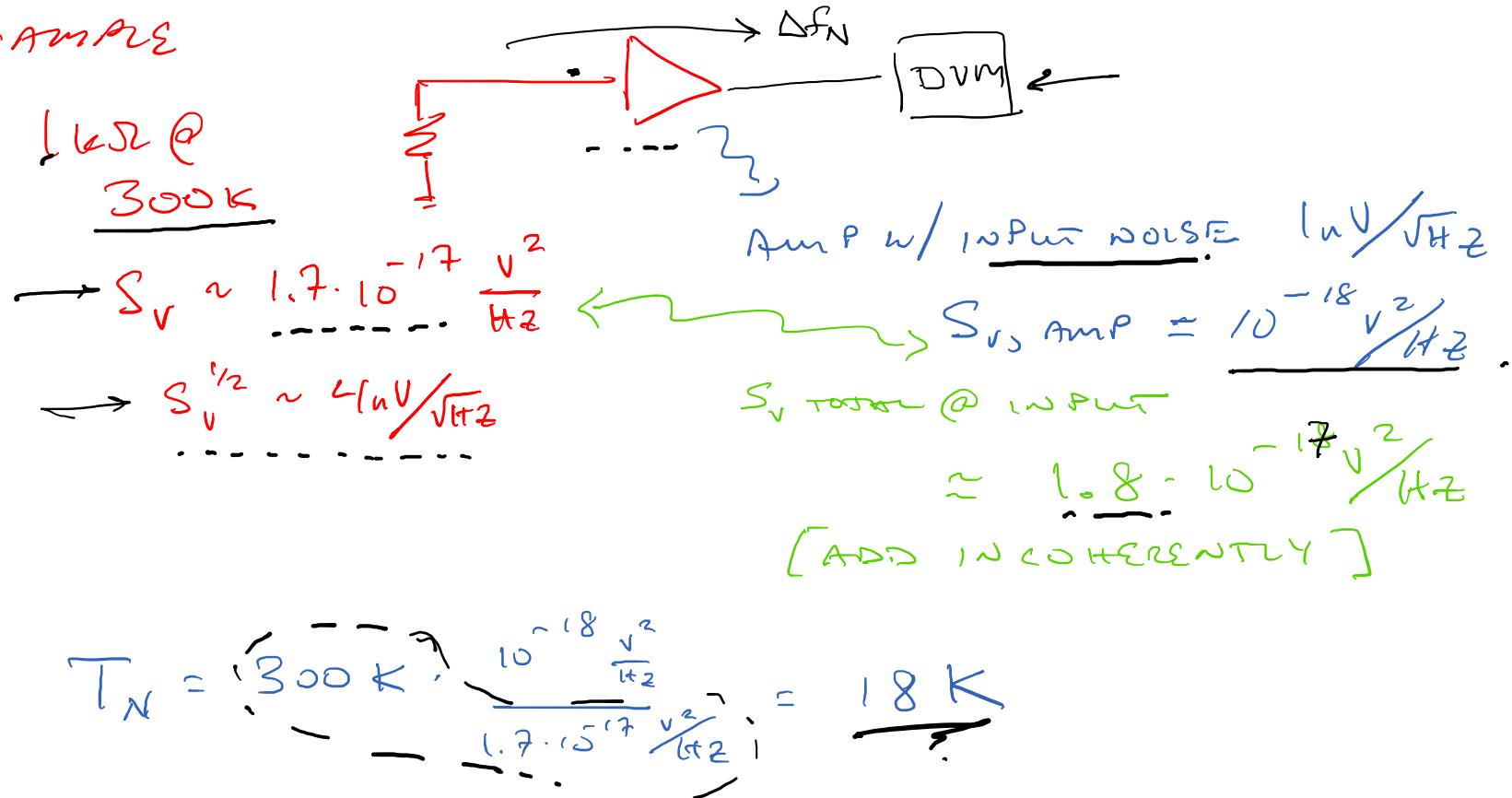
$$= G \left[4k_b T_s \Delta f_{in} + \text{AMP IN-PUT NOISE} \right] \leftarrow$$

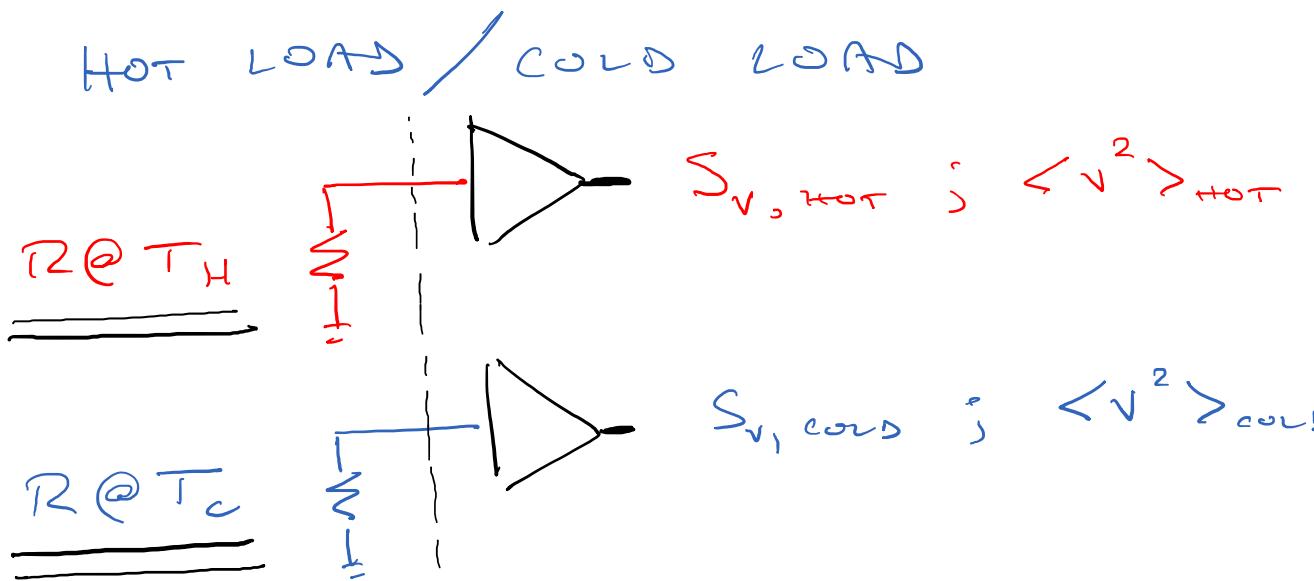
$$= G \left[4k_b R_s \Delta f_N (T + T_N) \right]$$

→ NOISE TEMPERATURE T_N

FUNCTION OF f ,
OF R_s

EXAMPLE





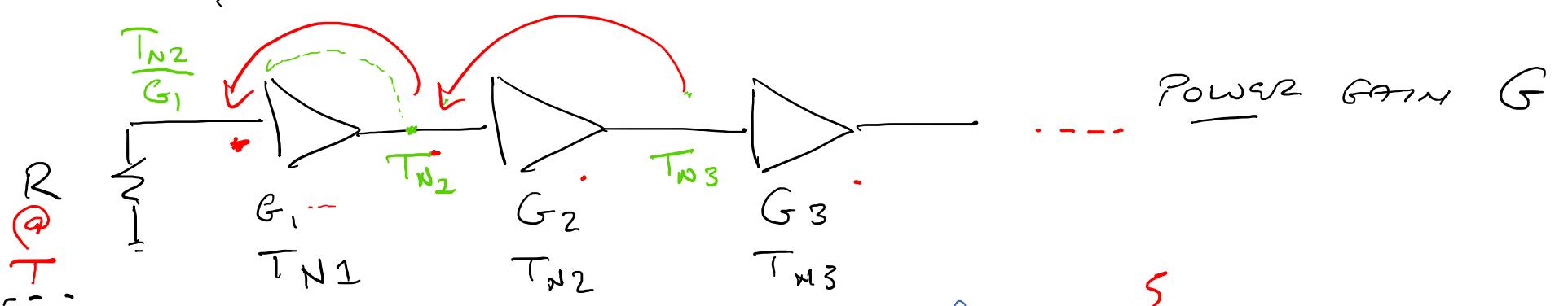
$$\frac{\langle v^2 \rangle_H}{\langle v^2 \rangle_C} = \frac{S_{v, HOT}}{S_{v, COLD}} = \frac{\overbrace{T_H + T_N}^2}{\overbrace{T_C + T_N}^2}$$

$$\frac{\langle v^2 \rangle_H}{\langle v^2 \rangle_C} = \frac{4k(T_H + T_N)R_{NFB}}{4k(T_C + T_N)R_{NFB}}$$

SELF-CALIBRATING

NOTE : T_x GENERALLY A FUNCTION OF FREQUENCY.

T_N of cascaded amplifiers



$$\text{noise power at output} \sim G_3 \left\{ G_2 \left[G_1 (T + T_{N1}) + T_{N2} \right] + T_{N3} \right\}$$

REFER TO INPUT

$$T_{N,\text{TOTAL}} = T_{N1} + \frac{T_{N2}}{G_1} + \frac{T_{N3}}{G_1 G_2} + \dots$$

Noise Figure

$$\rightarrow NF = 10 \log_{10} \left(\frac{T + T_N}{T_N} \right) \quad \overbrace{T=800K}$$

3

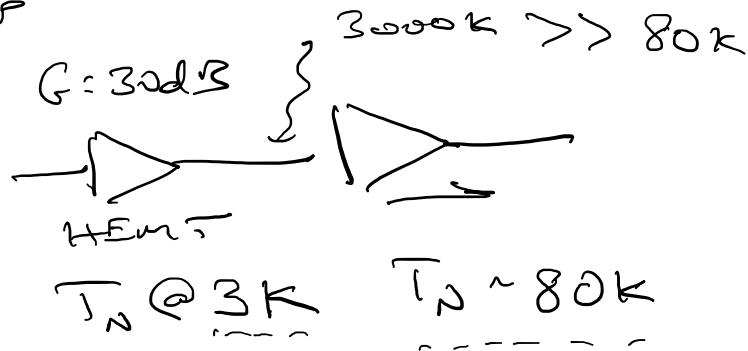
$$NF \sim 1 \text{ dB} \Leftrightarrow 80 \text{ K } T_N$$

$$3 \text{ dB} \Leftrightarrow 300 \text{ K } T_N$$

example

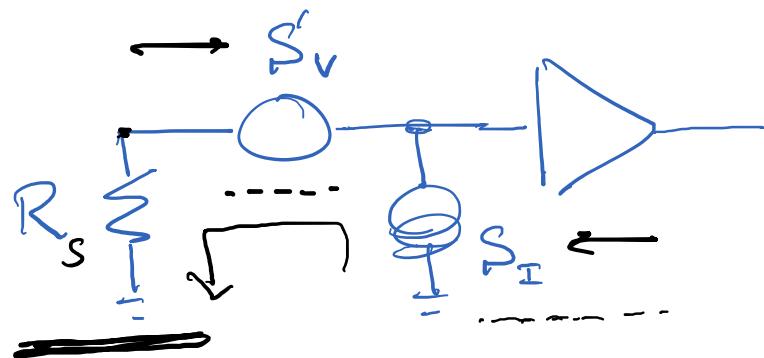
CASCaded

Ans



$$T_{P, \text{total}} = 3K + \frac{80K}{10^3} \approx \underline{\underline{3.08K}}$$

AMPLIFIER NOISE ... MORE DETAILS



$$S_v + S_I R_s^2 = 4 k_B T_N R_s$$

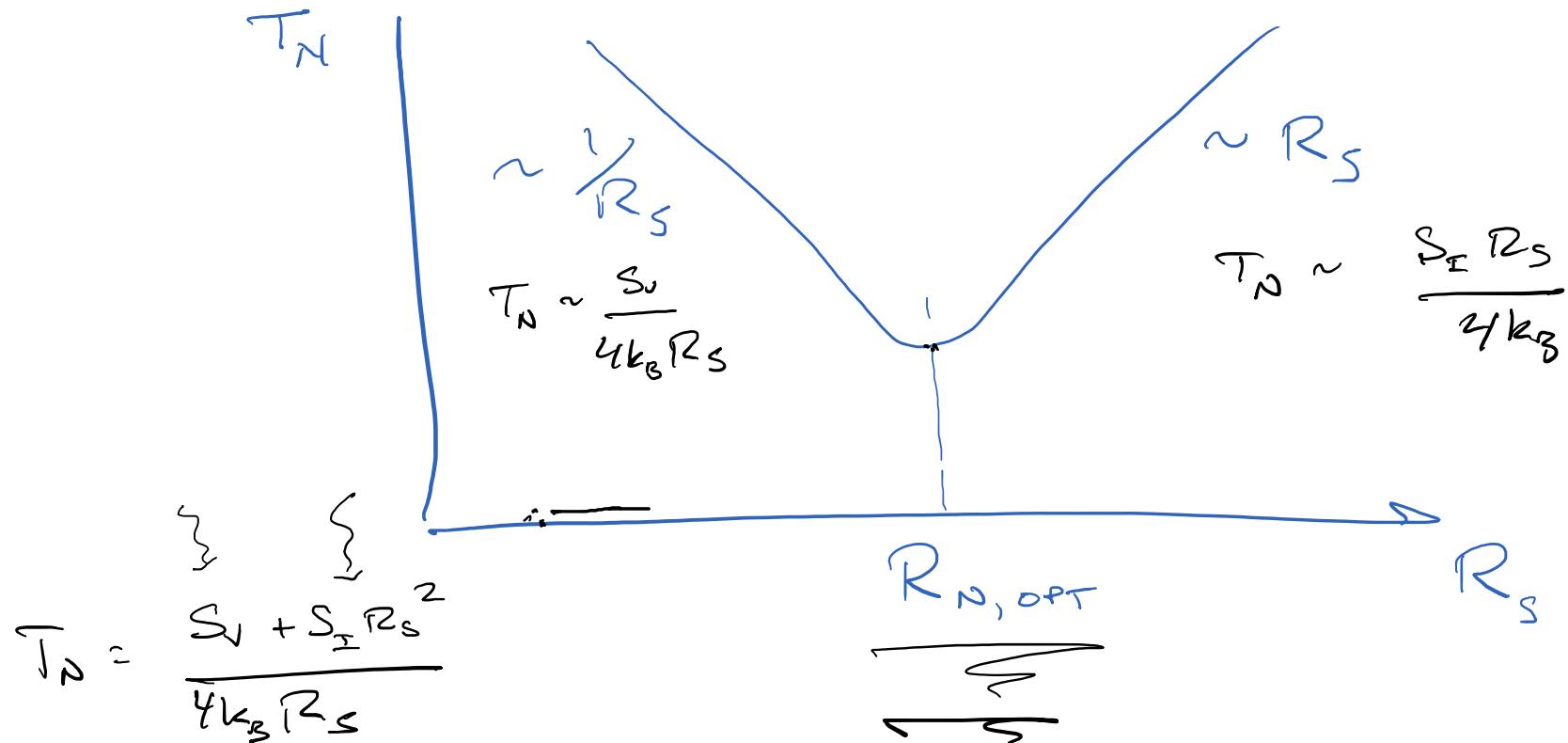
AMP CONTRIBUTION TO NOISE :

$$\rightarrow S_v + S_I R_s^2$$

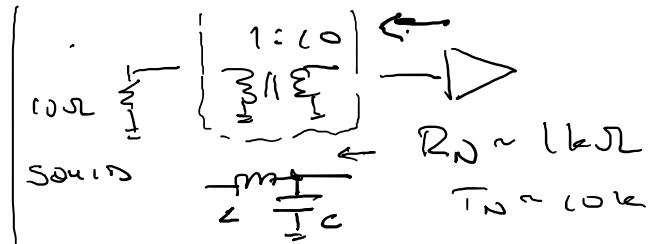
AMP NOISE TEMPERATURE :

$$T_N = \frac{S_v + S_I R_s^2}{4 k_B R_s}$$

DEPENDENCE ON SOURCE RESISTANCE



$$\rightarrow T_N = \frac{S_V + S_I R^2}{2(kR)}$$



$$\frac{\partial T_N}{\partial R} = 0 \Rightarrow -\frac{S_V}{R^2} + \frac{S_I}{2} = 0$$

$$\Rightarrow R_{N, OPT} = \sqrt{\frac{S_V}{S_I}}$$

→ Optimum Source Resistance

For Low Added Amplifier Noise

NOISE AMPLITUDE e_n OR v_n → $\frac{n\sqrt{kT_e}}{\sqrt{h+\epsilon}}$

i_n → $\frac{P_A}{\sqrt{h+\epsilon}}$

$$R_{N, OPT} = \frac{e_n}{i_n}$$

Other Noise Processes

SHOT NOISE $\sum I = 2eI \Rightarrow$ Due to discreteness or charge



POISSON STATISTICS

→ Mean-square current fluctuation

$$\frac{\langle \delta I^2 \rangle}{\text{---}} = \frac{Ne^2}{\Delta t^2} = \underline{\underline{I \frac{e}{\Delta t}}}$$

$N \rightarrow$ mean # of events per unit time.

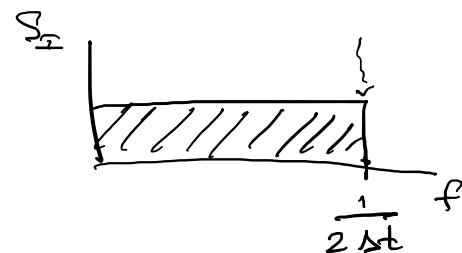
$$I = \frac{Ne}{\Delta t}$$

But $\underline{\underline{\langle \delta I^2 \rangle}} = S_I \frac{1}{2\Delta t}$

NYQUIST FREQUENCY

$$\underline{\underline{\langle \delta I^2 \rangle}} = \int S_I df$$

$$\therefore \underline{\underline{S_I}} = 2eI$$



TELEGRAPH NOISE



TWO-STATE SYSTEM

MEAN Dwell TIME \bar{t}

Recall, $S(t) = \int \langle v(t) v(0) \rangle e^{-2\pi f t} dt$

$$\langle v(t) v(0) \rangle = +1 \cdot P(\text{EVEN}) - 1 \cdot P(\text{ODD})$$

$$P_n(\lambda, t) = e^{-\lambda} \frac{\lambda^n}{n!}$$

$$\langle v(t) v(0) \rangle = e^{-\lambda} \left\{ \sum_{\text{EVEN}}^n \frac{\lambda^n}{n!} - \sum_{\text{ODD}}^n \frac{\lambda^n}{n!} \right\} = e^{-2\lambda}$$

$$\lambda = \frac{t}{\tau}$$

$$\therefore \langle v(t) v(0) \rangle = e^{-2t/\tau}$$

$$S(f) = \int e^{-2t/\tau} e^{-2\pi f t} dt$$

$$S(f) = \frac{\tau}{1 + 4(2\pi f \tau)^2}$$

