DE-Nano

My First Nios II for Altera DE-Nano Board







CONTENTS

| CHAPTER 1 HARDWARE DESIGN | |
|--|----|
| | |
| 1.1 Required Features | |
| 1.2 Creation of Hardware Design | |
| 1.3 DOWNLOAD HARDWARE DESIGN TO TARGET FPGA | 68 |
| | |
| CHAPTER 2 NIOS II SOFTWARE BUILD TOOLS FOR ECLIPSE | 71 |
| 2.1 Create the hello_world Example Project | 71 |
| 2.2 BUILD AND RUN THE PROGRAM | 76 |
| 2.3 EDIT AND RE-RUN THE PROGRAM | 78 |
| 2.4 WHY THE LED BLINKS | 80 |
| 2.5 DEBUGGING THE APPLICATION | 82 |
| 2.6 CONFIGURE BSP EDITOR | 83 |



Chapter 1

Hardware Design

This tutorial provides comprehensive information that will help you understand how to create a FPGA based SOPC system implementing on your FPGA development board and run software upon it.

1.1 Required Features

The Nios II processor core is a soft-core central processing unit that you could program onto an Altera field programmable gate array (FPGA). This tutorial illustrates you to the basic flow covering hardware creation and software building. You are assumed to have the latest Quartus II and NIOS II EDS software installed and quite familiar with the operation of Windows OS. If you use a different Quartus II and NIOS II EDS version, there will have some small difference during the operation. You are also be assumed to possess a DE-Nano development board (other kinds of dev. Board based on Altera FPGA chip also supported).

The example NIOS II standard hardware system provides the following necessary components:

- Nios II processor core, that's where the software will be executed
- On-chip memory to store and run the software
- JTAG link for communication between the host computer and target
- hardware (typically using a USB-BlasterII cable)
- LED peripheral I/O (PIO), be used as indicators

1.2 Creation of Hardware Design

This section describes the flow of how to create a hardware system including SOPC feature.

1. Launch Quartus II then select File->New Project Wizard, start to create a new project. See Figure 1-1 and Figure 1-2.



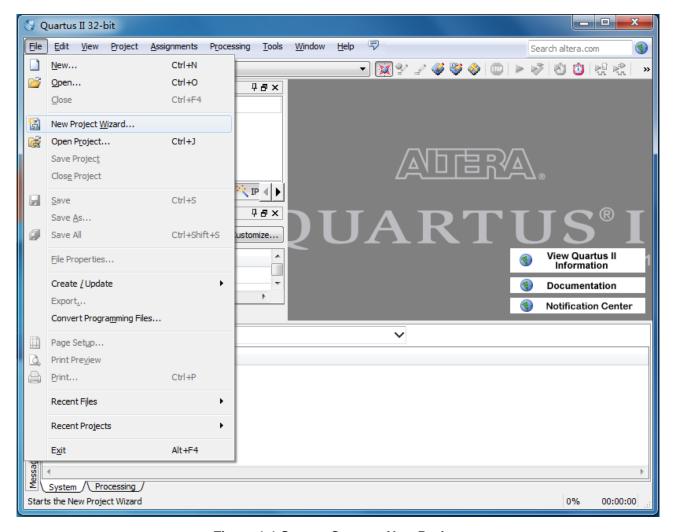


Figure 1-1 Start to Create a New Project



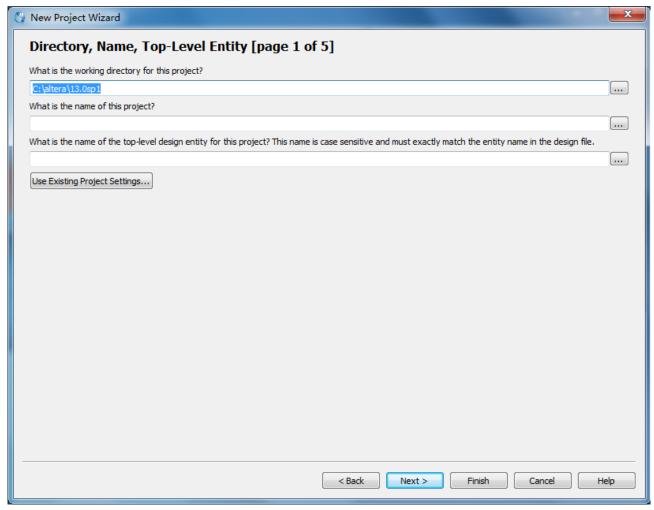


Figure 1-2 New Project Wizard

2. Choose a working directory for this project, type project name and top-level entity name as shown in **Figure 1-3**. Then click Next, you will see a window as shown in **Figure 1-4**.



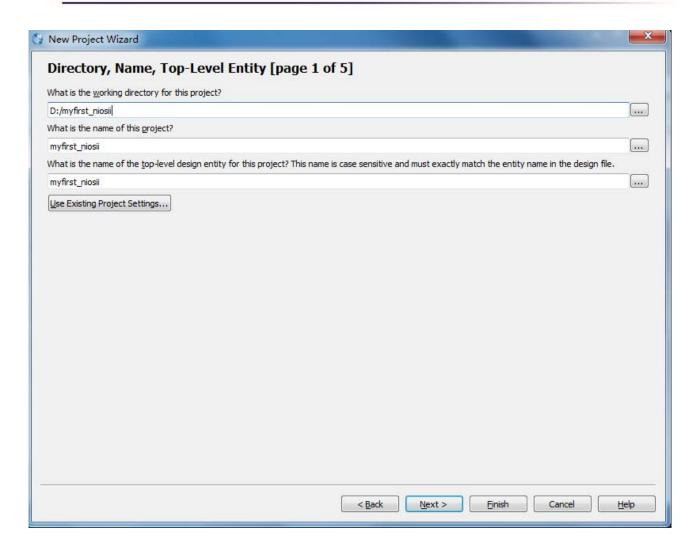


Figure 1-3 Input the working directory, the name of project, top-level design entity



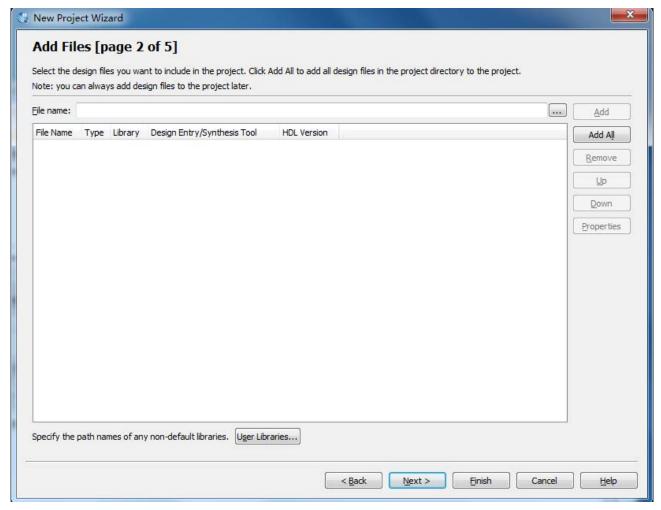


Figure 1-4 New Project Wizard: Add Files [page 2 of 5]

3. Click Next to next window. We choose device family and device settings. You should choose settings the same as the **Figure 1-5**. Then click Next to next window as shown in **Figure 1-6**.



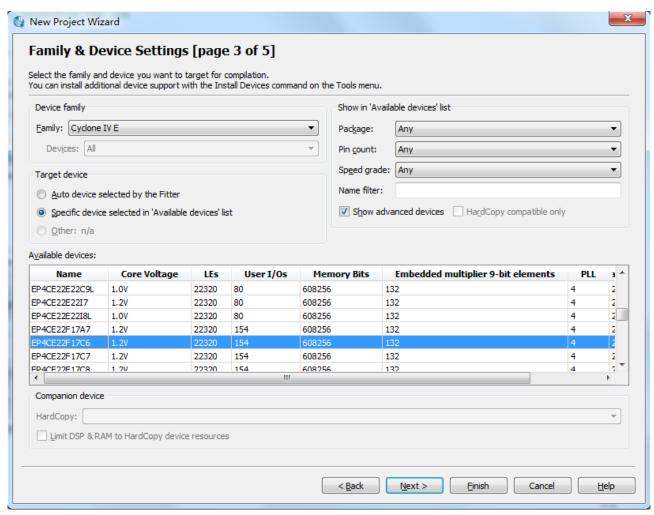


Figure 1-5 New Project Wizard: Family & Device Settings [page 3 of 5]



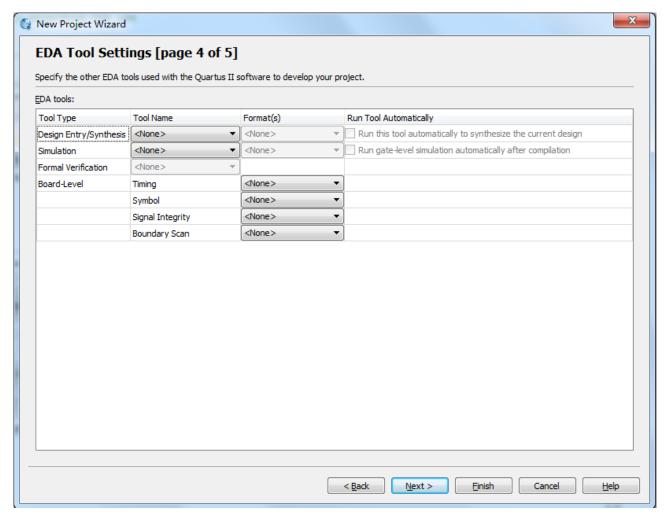


Figure 1-6 New Project Wizard: EDA Tool Settings [page 4 of 5]

4. Click Next and will see a window as shown in **Figure 1-7**. **Figure 1-7** is a summary about our new project. Click Finish to finish new project. **Figure 1-8** show a new complete project.



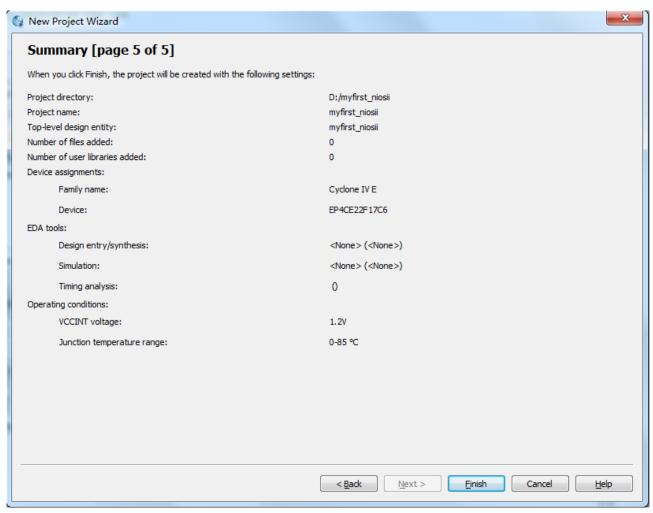


Figure 1-7 New Project Wizard: Summary [page 5 of 5]



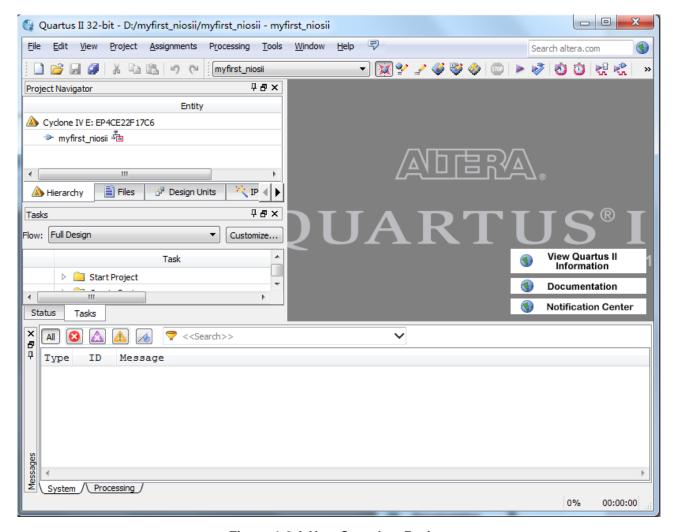


Figure 1-8 A New Complete Project

5. Choose **Tools** > **Qsys** to open new **Qsys** system wizard . See **Figure 1-9** and **Figure 1-10**.



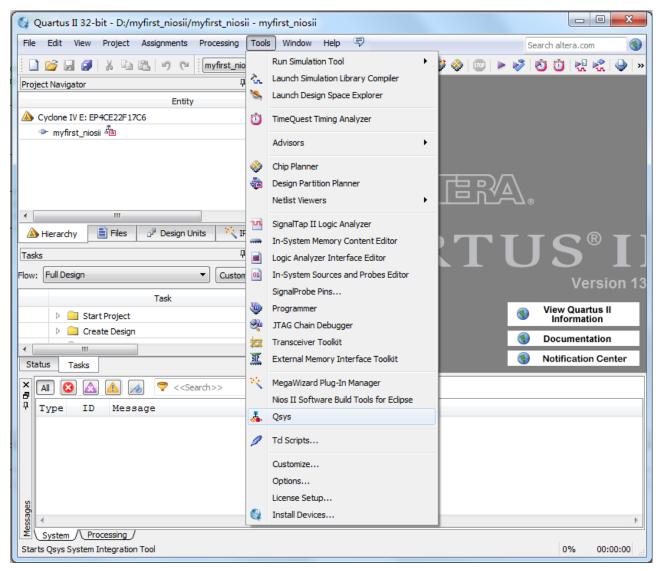


Figure 1-9 Qsys Menu



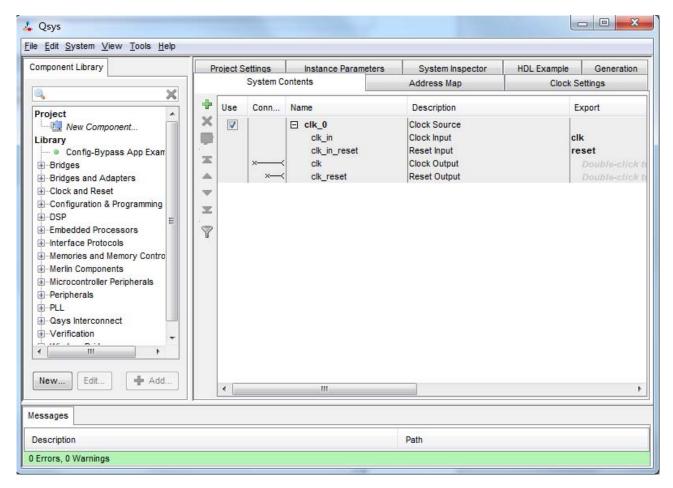


Figure 1-10 Create New Qsys System

6. Save as the System as shown in **Figure 1-11**.



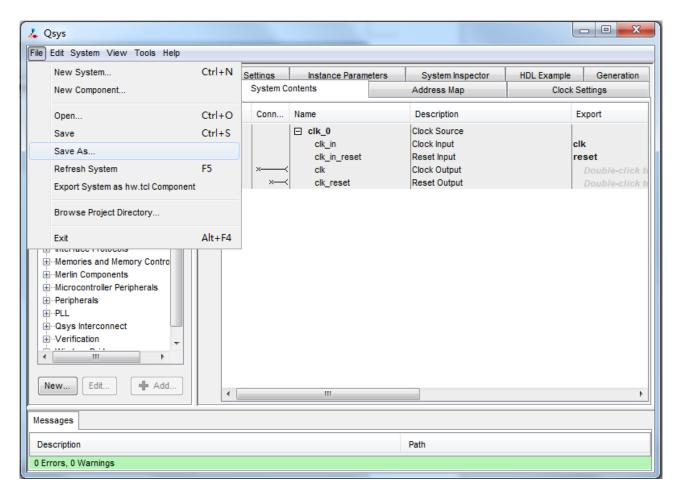


Figure 1-11 Save System

7. Rename System Name as shown in **Figure 1-12**. Click Save and your will see a window as shown in **Figure 1-13**.



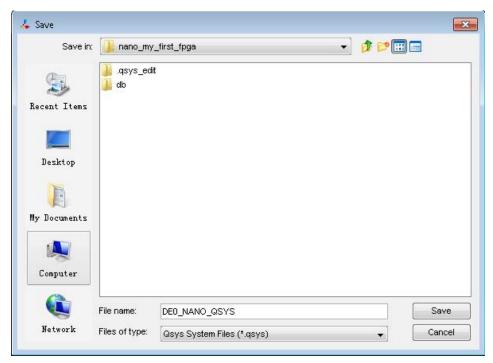


Figure 1-12 Rename System

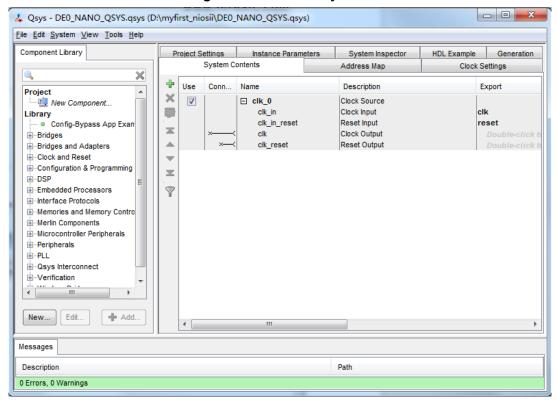


Figure 1-13 A New System

8. Click the Name of the Clock Settings table, rename clk_0 to clk_50. Press Enter to complete the update. See **Figure 1-14**.





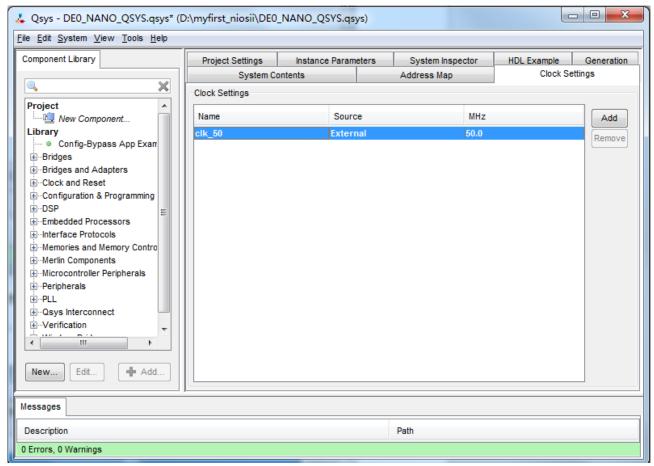


Figure 1-14 Rename Clock Name

9. Choose Library > Embedded Processors > Nios II Processor to open wizard of adding cpu component. See **Figure 1-15** and **Figure 1-16**.



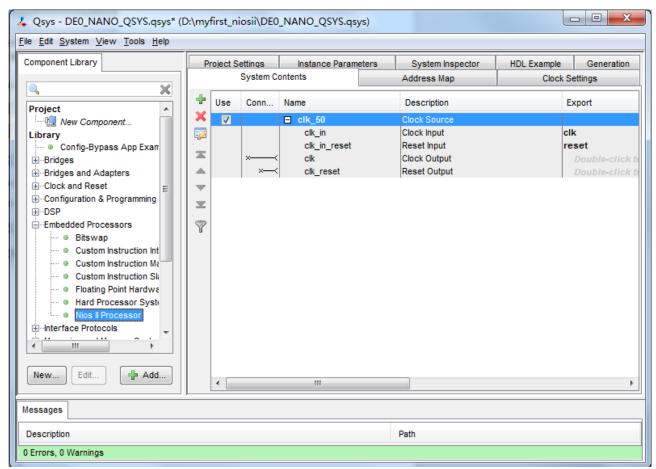


Figure 1-15 Add Nios II Processor



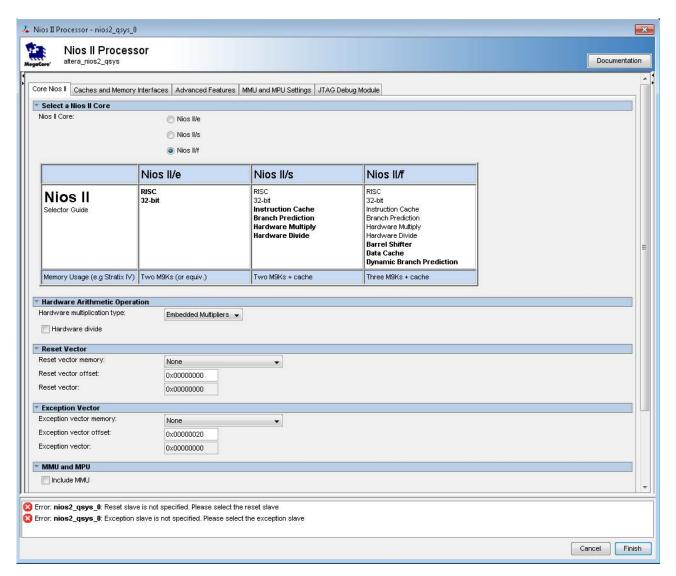


Figure 1-16 Nios II Processor

10. Click Finish to return to main window as shown in Figure 1-17.



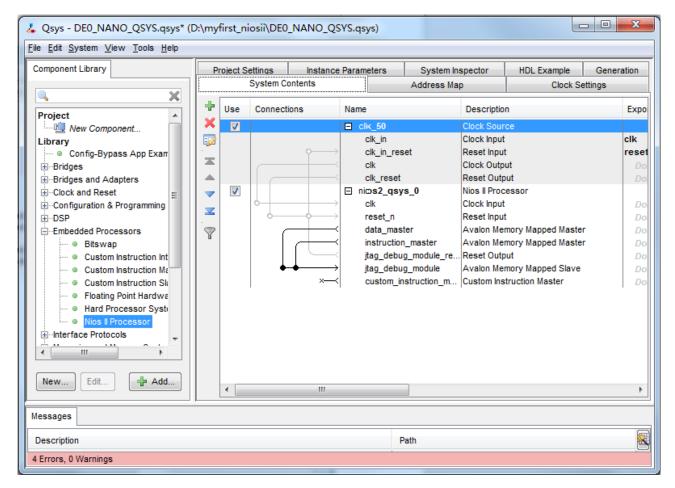


Figure 1-17 Add Nios II CPU completely

11. Choose nios2_qsys_0 and right-click then choose rename, after this, you can update nios2_qsys_0 to cpu. See **Figure 1-18** and **Figure 1-19**.



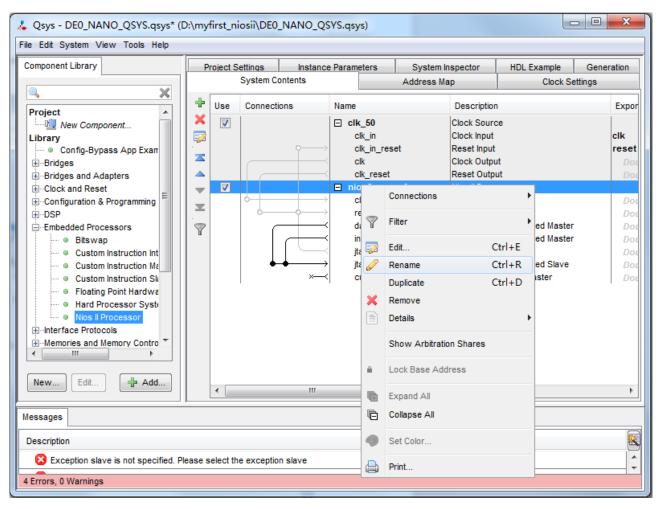


Figure 1-18 Rename CPU name (1)



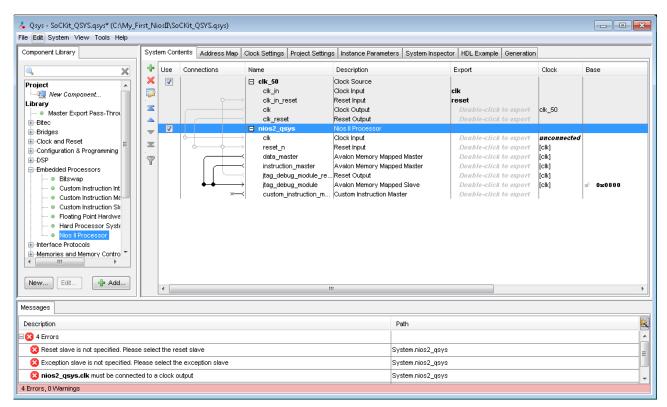


Figure 1-19 Rename CPU Name (2)

11. Connect the clk and clk_reset as shown in **Figure 1-20**. (clicking the hollow dots on the connection line. The dots become solid indicatingthe ports are connected.)



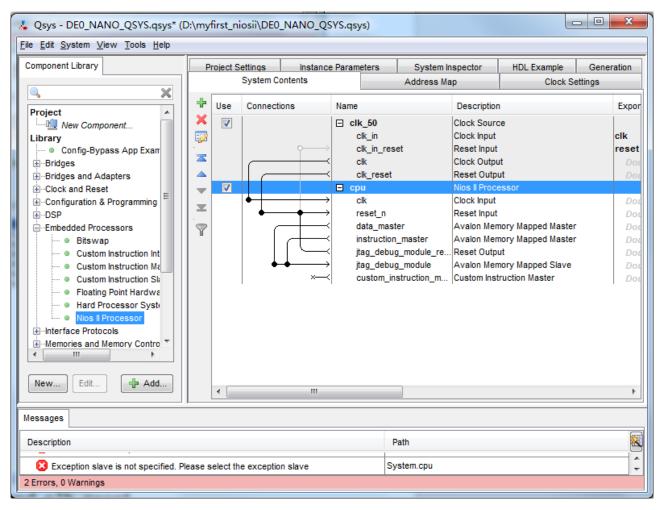


Figure 1-20 Connect the clk and clk_reset

12. Choose Library > Interface Protocols > Serial > JTAG UART to open wizard of adding JTAG UART. See **Figure 1-21** and **Figure 1-22**.



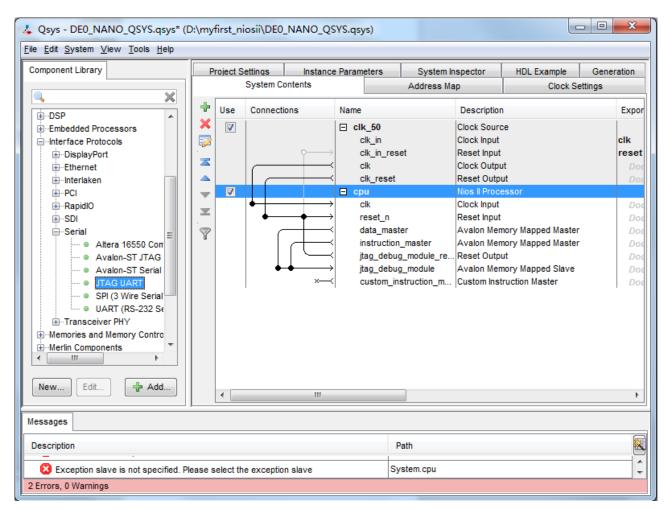


Figure 1-21 Add JTAG UART (1)



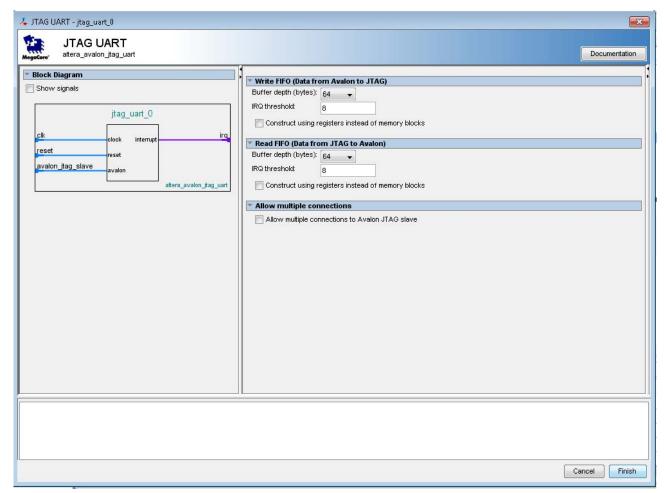


Figure 1-22 JTAG UART (2)

13. Click **Finish** to close the wizard and return to the window as shown in **Figure 1-**.



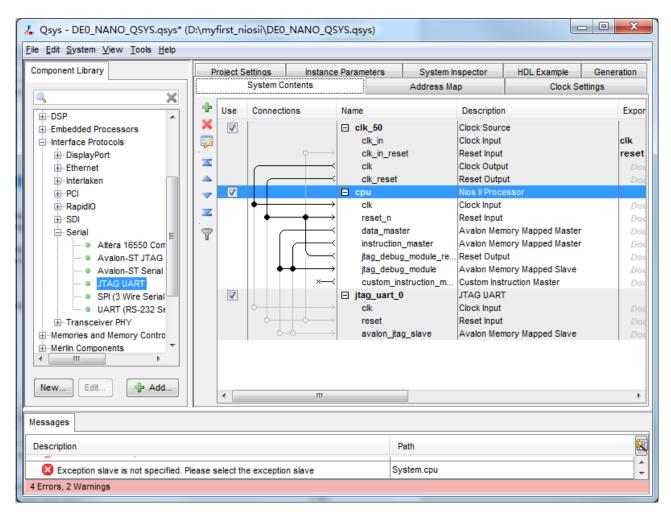


Figure 1-23 JTAG UART

14. Choose **jtag_uart_0** and rename it to **jtag_uart** as shown in **Figure 1-**.



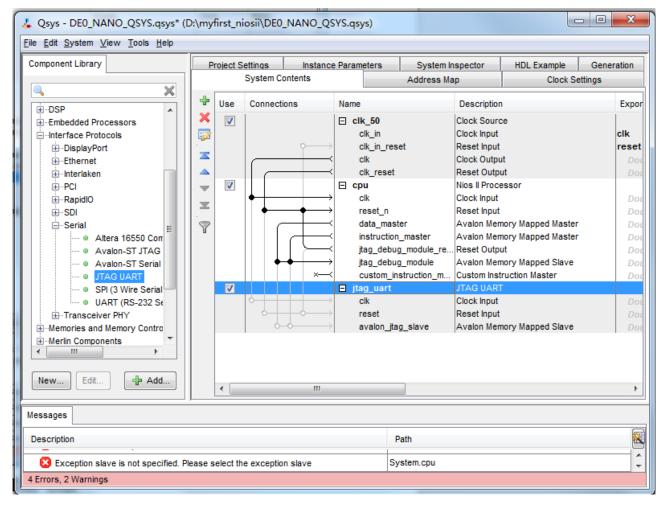


Figure 1-24 Rename JTAG UAR

15. Connect the **clk** and **clk_reset** and **data_master** as shown in **Figure 1-5**.



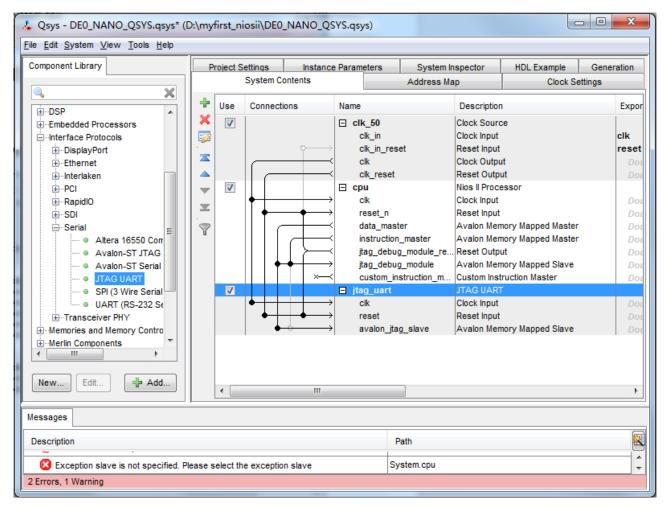


Figure 1-25 Connect JTAG UART

16. Choose Library > Memories and Memory Controllers > On-Chip > On-Chip Memory (RAM or ROM) to open wizard of adding On-Chip memory. See **Figure 1-** and **Figure 1-**.



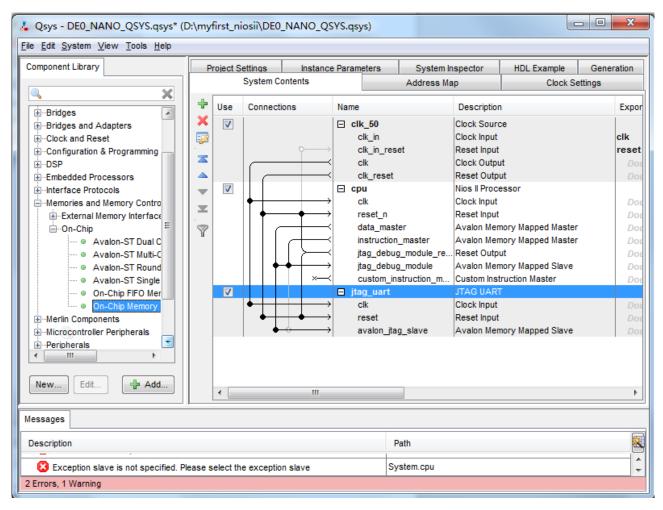


Figure 1-26 Add On-Chip Memory



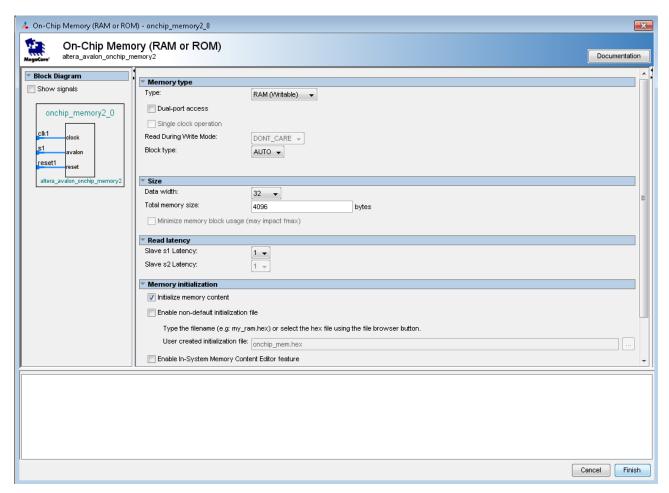


Figure 1-27 On-Chip Memory Box

17. Modify Total memory size to 32768 as shown in **Figure 1-**. Click Finish to return to the window as in **Figure 1-29**.



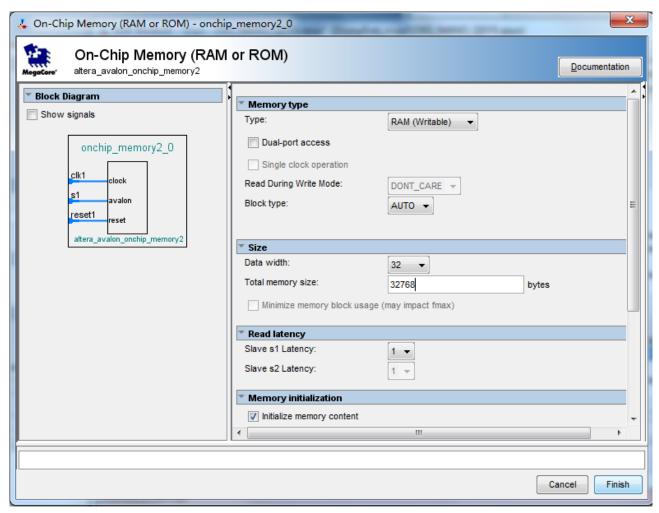


Figure 1-28 Update Total memory size



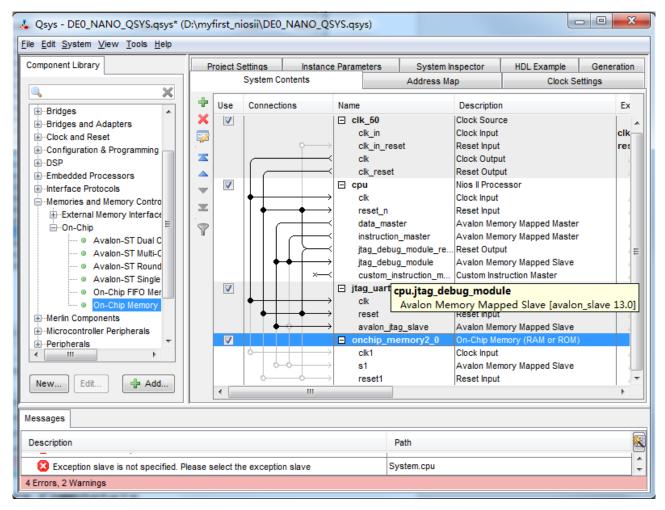


Figure 1-29Add On-Chip memory Completely

18. Rename onchip_memory2_0 to onchip_memory2 as shown in Figure 1-30.



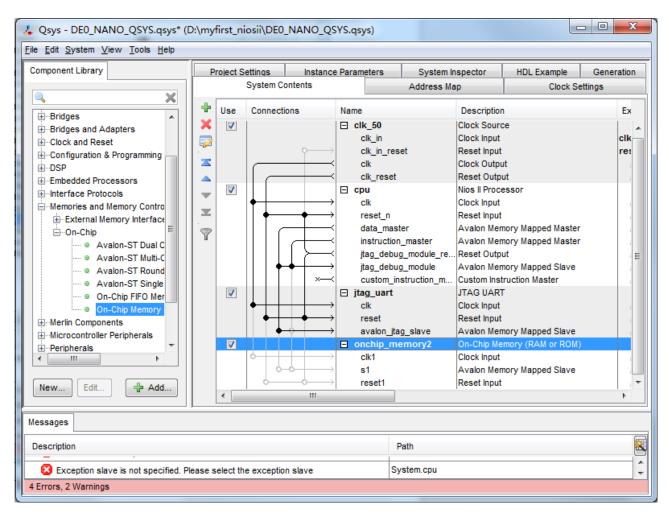


Figure 1-30 Rename On-Chip memory

19. Connect the **clk** and **clk_reset** and **data_master** as shown in **Figure 1-**.



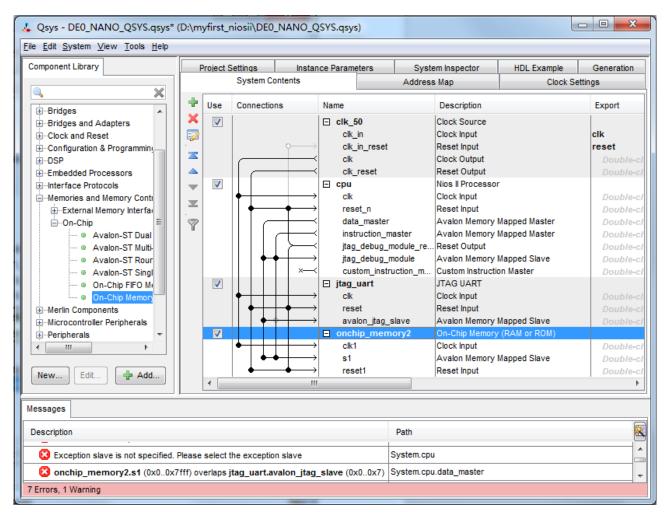


Figure 1-31 Connect On-Chip memory

20. Click **cpu** in the component list on the right part to edit the component. Update **Reset vector** and **Exception Vector** as shown in **Figure 1-32**. Then click **Finish** to return to the window as shown **Figure 1-33**.



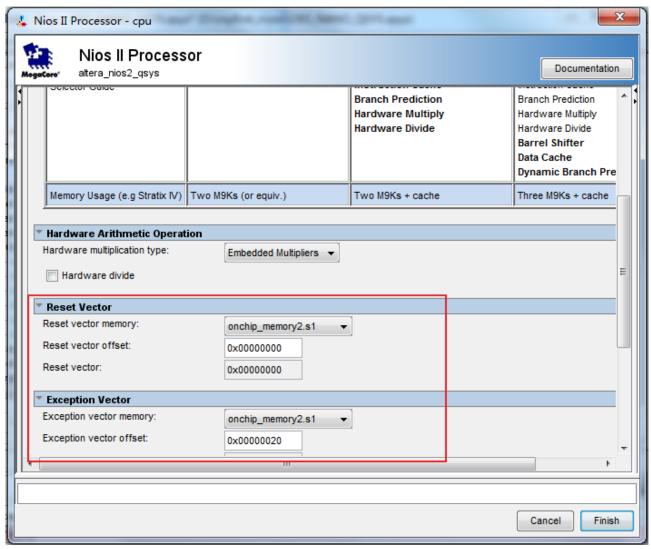


Figure 1-32 Update CPU settings



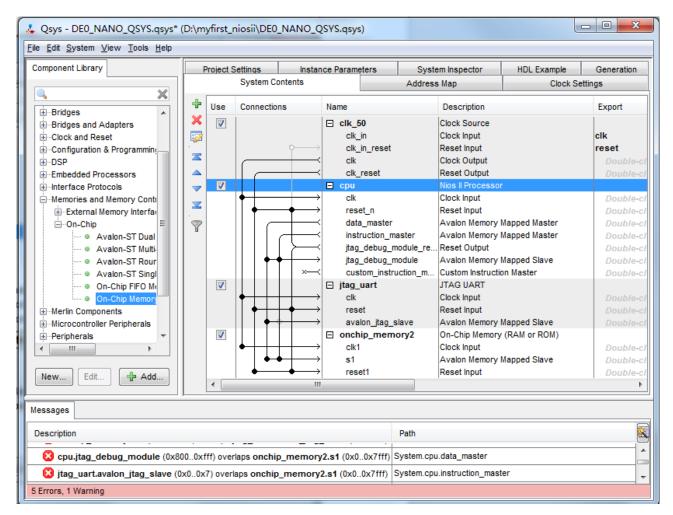


Figure 1-33 Update CPU settings Completely

21. Choose **Library** > **Peripherals** > **Debug and Performance** >**System ID Peripheral** to open wizard of adding **System ID**. See **Figure 1-** and **Figure 1-**.



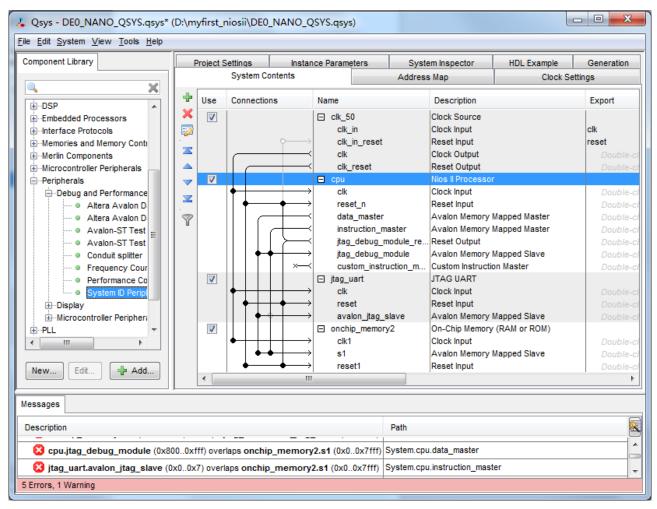


Figure 1-34 Add System ID [0]



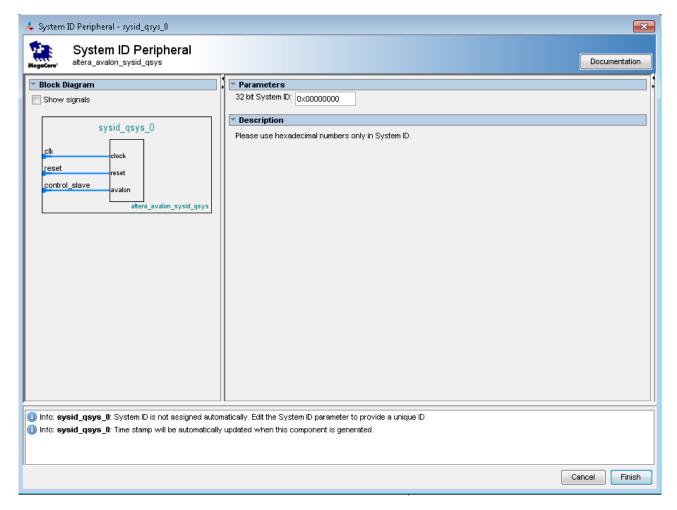


Figure 1-35 Add System ID [1]

22. Click **Finish** to close System ID Peripheral box and return to the window, rename **sysid_qsys_0** to **sysid** and connect the **clk** and **clk_reset** and **data_master** as shown in **Figure 1-**.



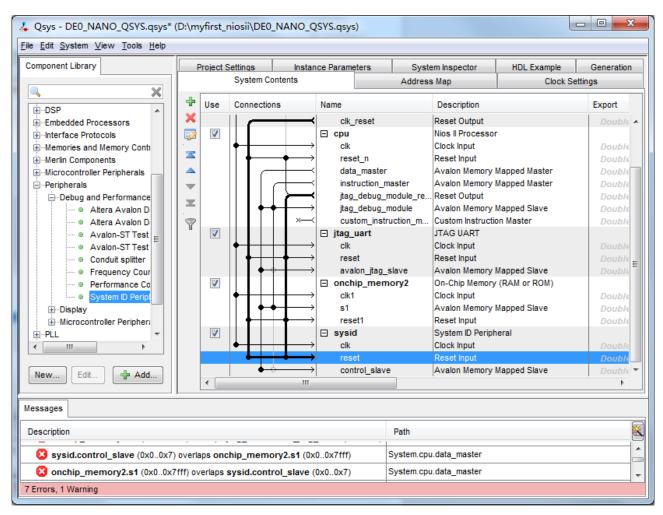


Figure 1-36 Add System ID [2]

23. Choose Library > Peripherals > Microcontroller Peripherals > PIO (Parallel I/O) to open wizard of adding PIO. See Figure 1- and Figure 1-.



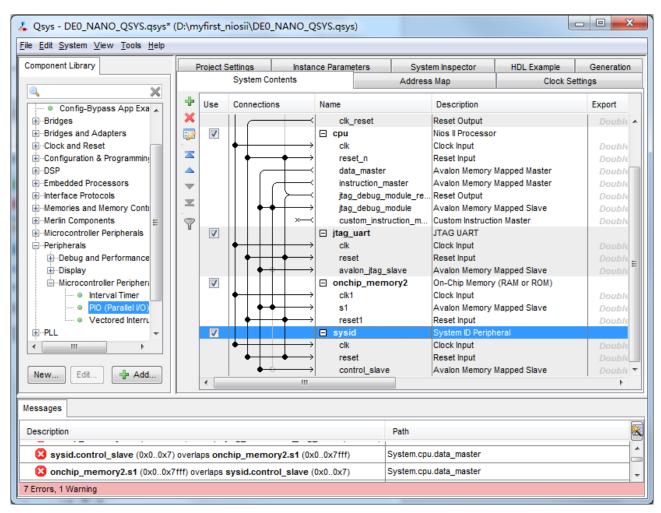


Figure 1-37 Add PIO





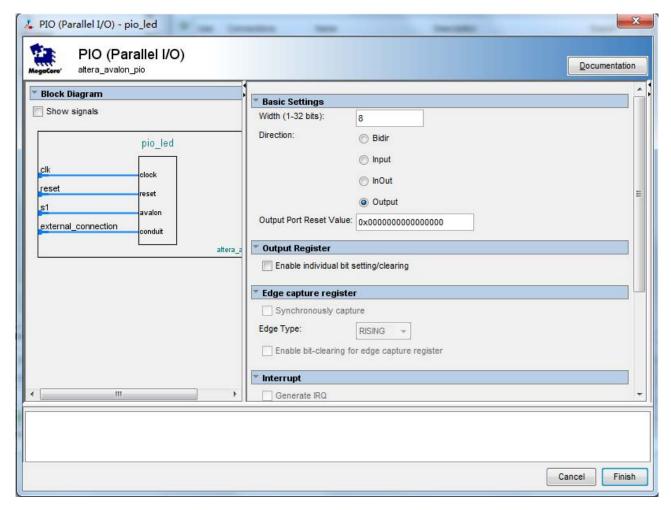


Figure 1-38 Add PIO

24. Click **Finish** to close PIO box and return to the window as shown in **Figure 1-**.



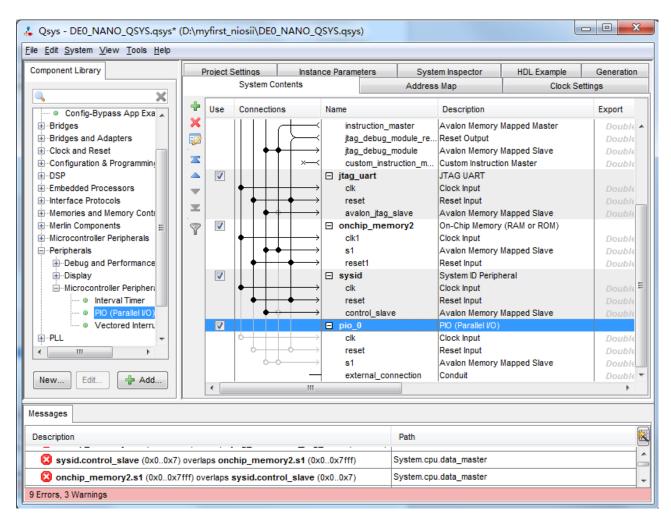


Figure 1-39 PIO

25. Rename pio_0 to pio_led as shown in Figure 1-40.





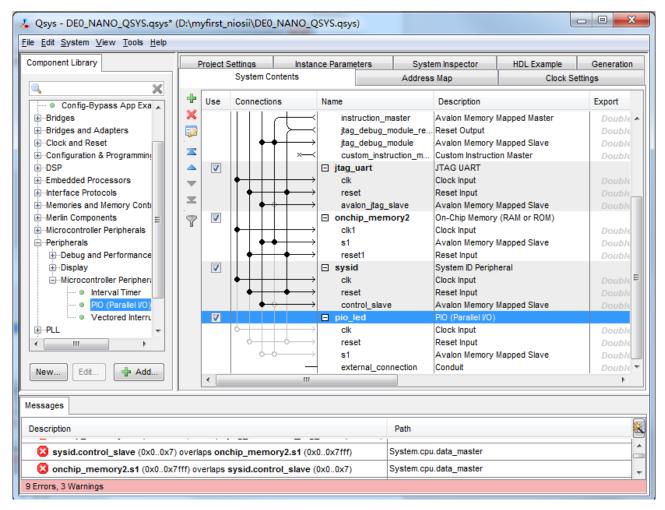


Figure 1-40 Rename PIO

26. Connect the clk and clk_reset and data_master as shown in Figure 1-.



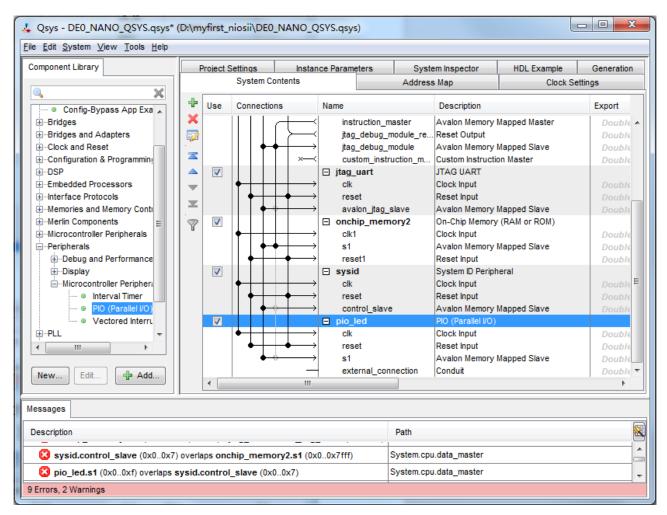


Figure 1-41 Connect PIO

27. Export external_connection and Rename it to pio_led_external_connection as shown in **Figure**1-.



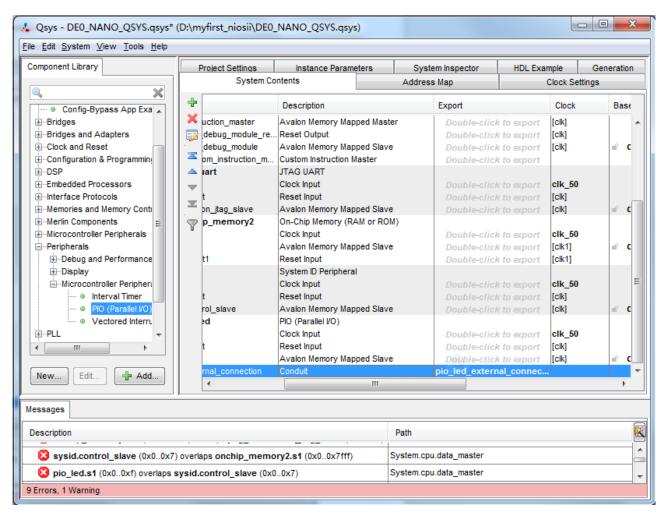


Figure 1-42 Export external_connection

28. Choose System > Assign Base Addresses as shown in **Figure 1-43**. After that, you will find that there is no error in the message window as shown in **Figure 1-44**.



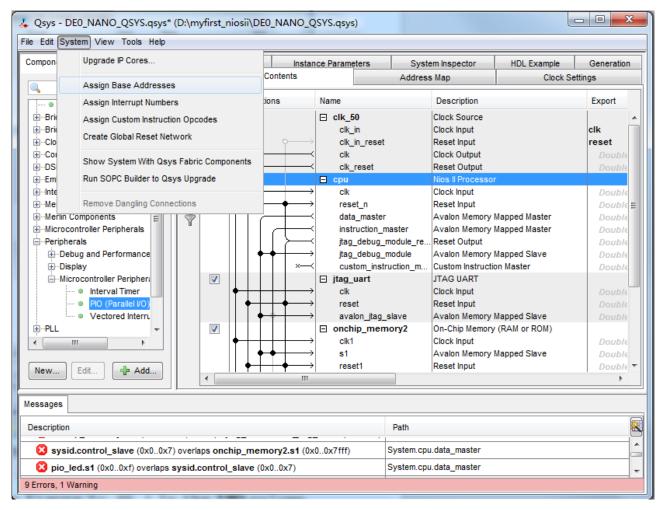


Figure 1-43 Assign Base Addresses



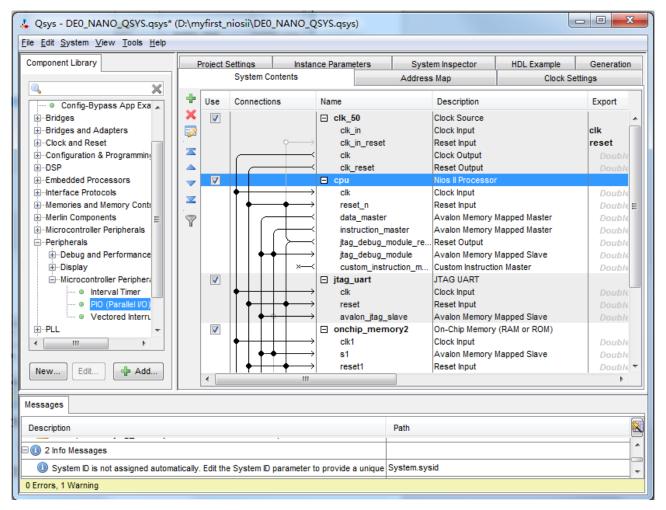


Figure 1-44 No Errors

29. Assign Interrupt Numbers as shown in **Figure 1-45**. After that, you will find that there is no warings in the message window as shown in **Figure 1-46**.(In the IRQ column, connect the Nios II processor to the JTAG UART)



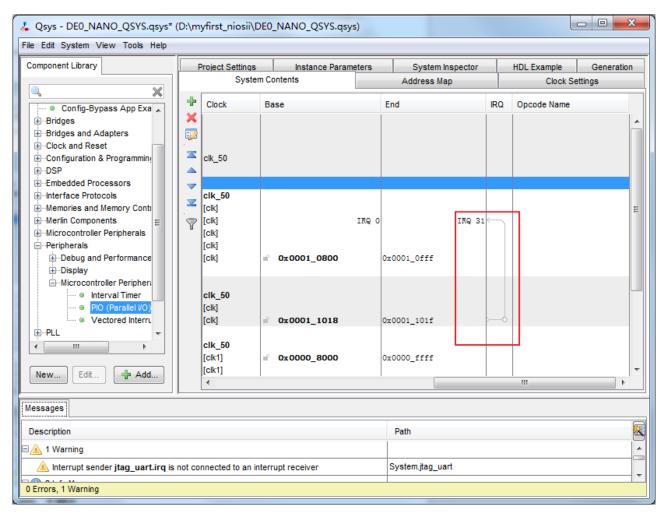


Figure 1-45 Assign IRQ



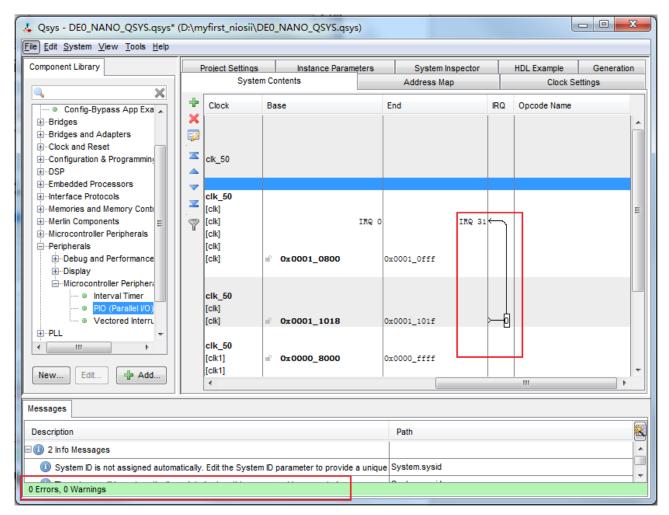


Figure 1-46 No Warings

30. Click Generate tab and click Generate then pop a window as shown in **Figure 1-**. Click Save and the generation start. **Figure 1-** shows the generate process. If there is no error in the generation, the window will show successful as shown in **Figure 1-**.



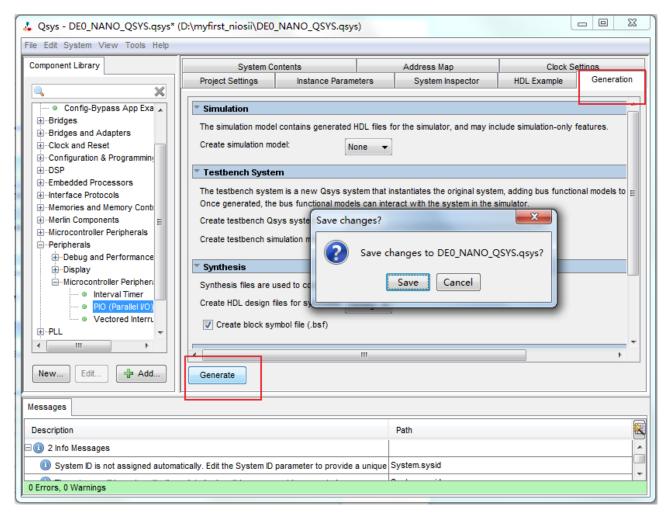


Figure 1-47 Generate Qsys





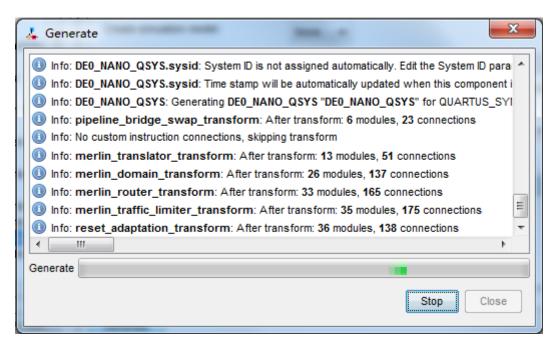


Figure 1-48 Generate Qsys

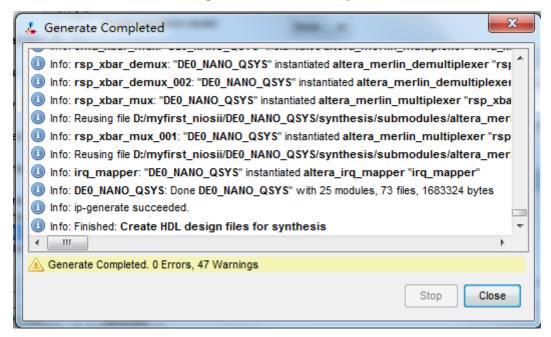


Figure 1-49 Generate Qsys Completely

31. Click **Close** to close the dialog box and **exit** the **Qsys** and return to the window as shown in **Figure 1-.**



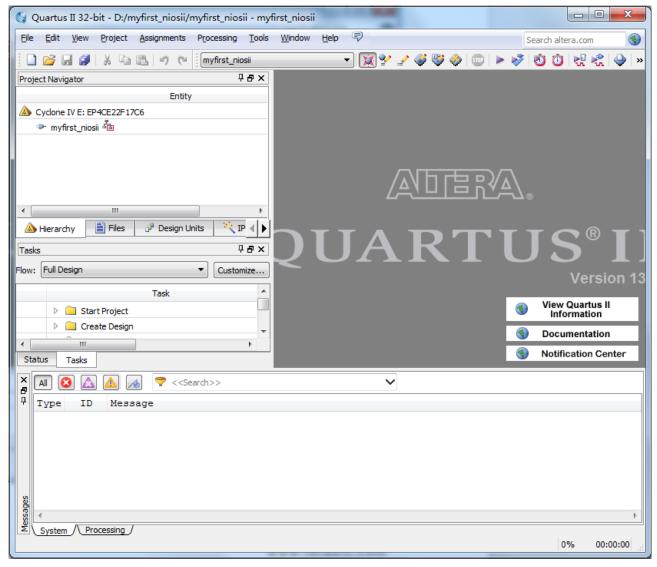


Figure 1-50 Exit Qsys

32. Choose **File** > **New** to open new files wizard. See **Figure 1-** and **Figure 1-**.



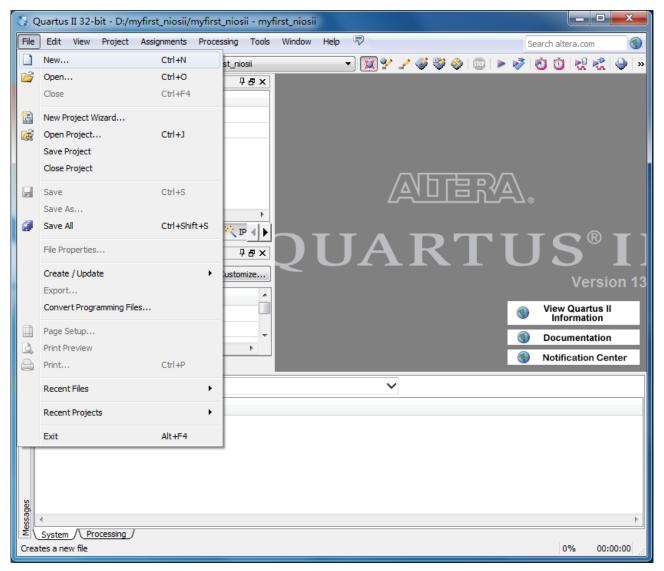


Figure 1-51 New Verilog file



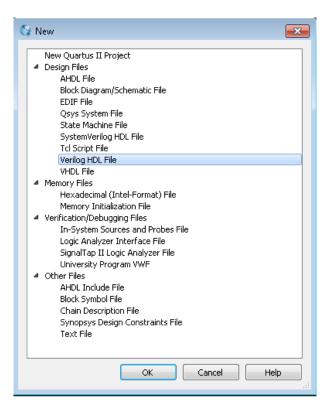


Figure 1-52 New Verilog File

33. Choose Verilog HDL File and click OK to return to the window as shown in **Figure 1**-. **Figure 1**- show a blank verilog file.



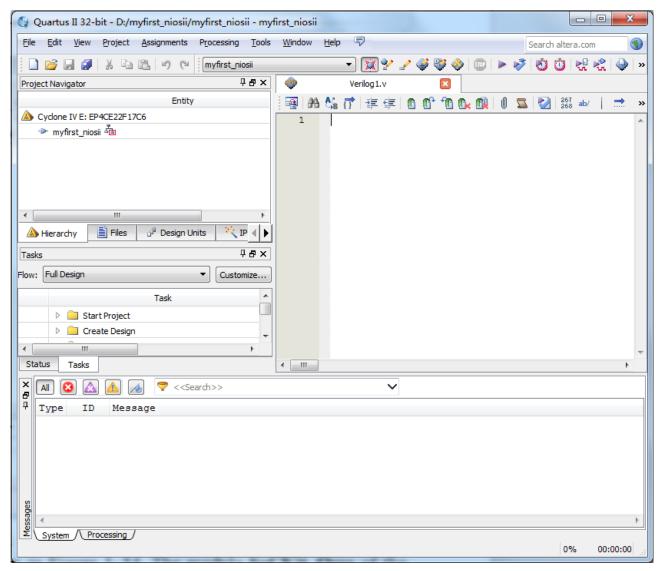


Figure 1-53 A blank verilog file

34. Type verilog the following script as shown in **Figure 1-54**. The module **DE0_NANO_QSYS** of the code is from **DE0_NANO_QSYS.v** of the project. See



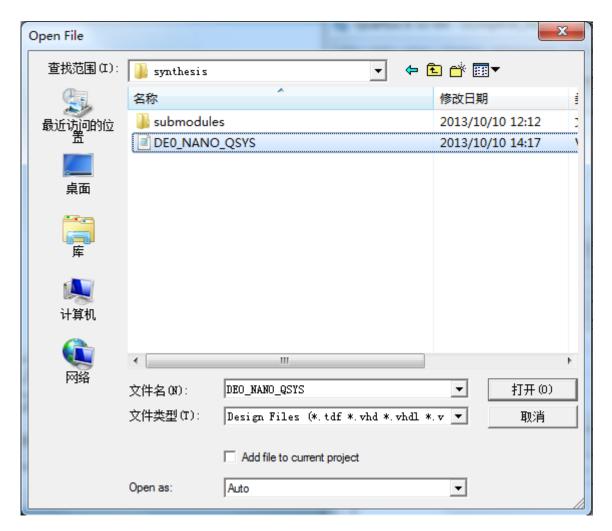


Figure 1-55 and Figure 1-56.

ter asiC

```
module myfirst_niosii

(

CLOCK_50,

LED

);

input CLOCK_50;

output [7:0] LED;
```



DE0 NANO QSYS DE0 NANO QSYS inst

```
.clk_50 (CLOCK_50),
.out_port_from_the_pio_led (LED),
.reset_n (1'b1)
```

endmodule

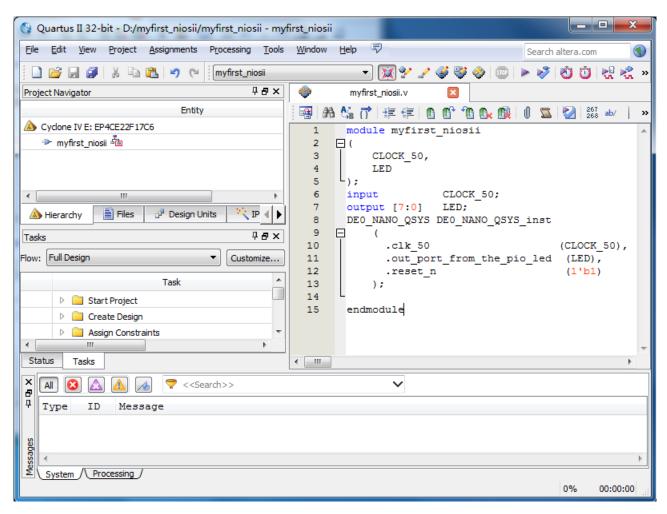


Figure 1-54 Input verilog Text

54

_



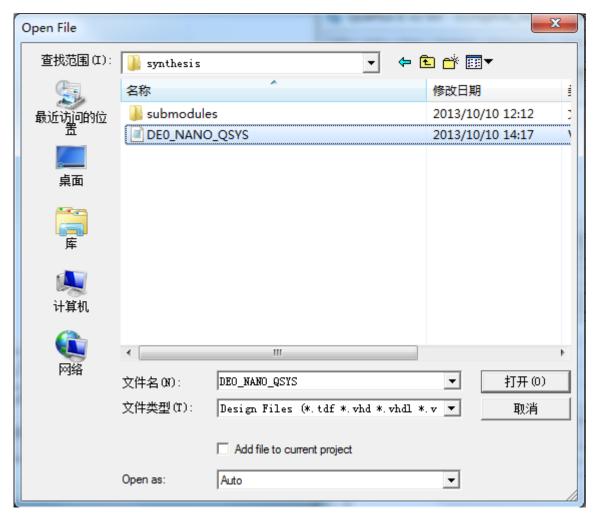


Figure 1-55 Open SoCKit_QSYS.v



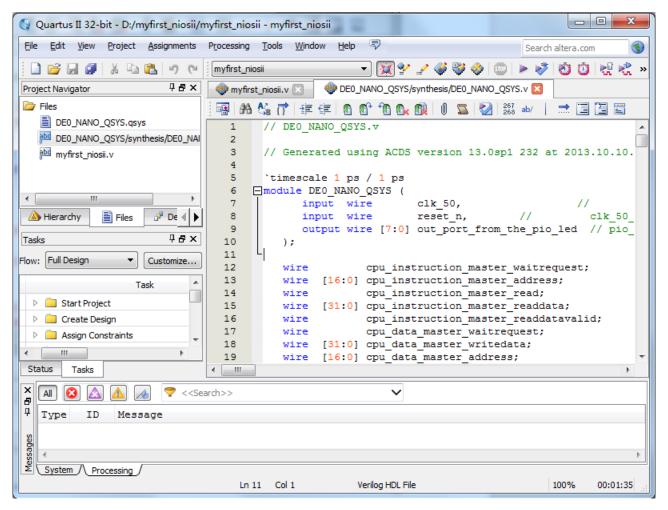


Figure 1-56 SoCKit_QSYS module

35. Choose **Save** Icon in the tool bar. There will appear a window as shown in **Figure 1-57**. Click **Save**.





Figure 1-57 Save Verilog file

36. Add File in project as shown in **Figure 1-58**, add DE0_NANO_QSYS.qsys and DE0_NANO_QSYS.v to the project as shown in **Figure 1-59** and **Figure 1-60**. it is completed as shown in Figure 1-.



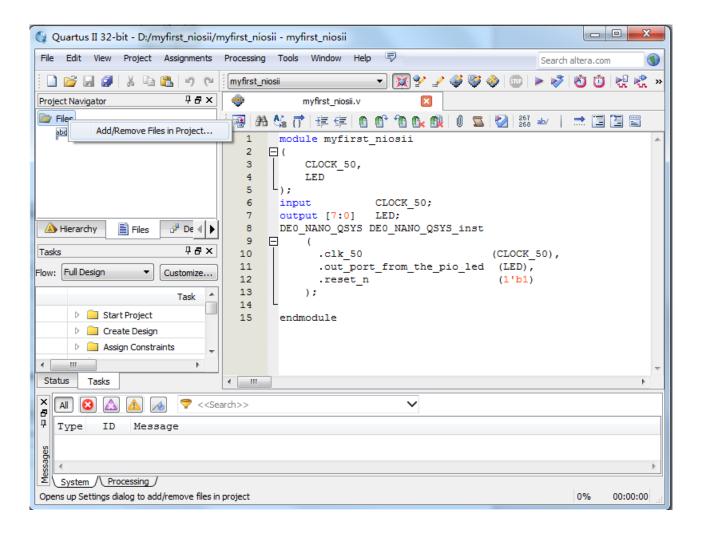


Figure 1-58 Add file





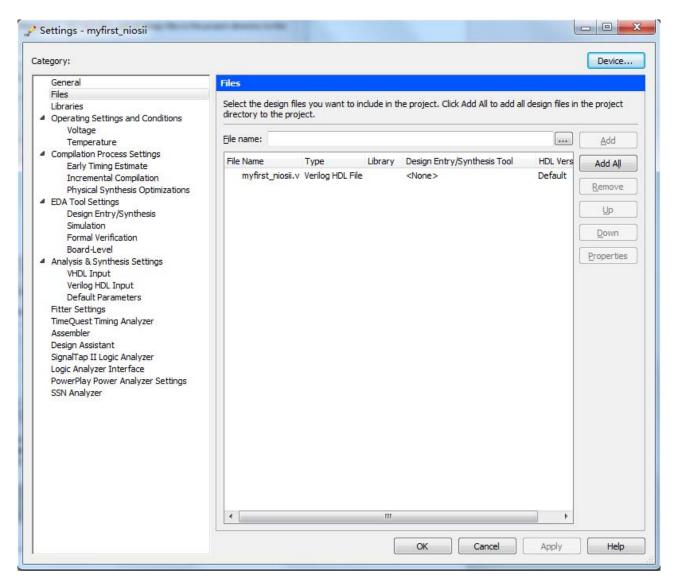


Figure 1-59 Add file



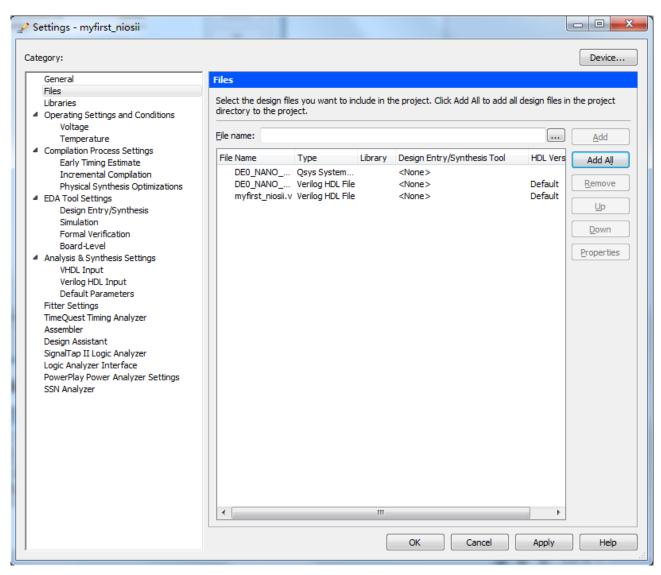


Figure 1-60 Add file



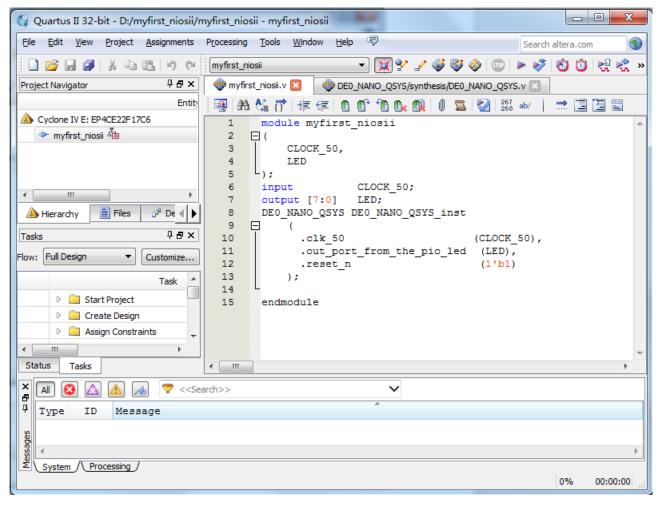


Figure 1-61 Add file completely

37. Choose Processing > Start Compilation as shown in **Figure 1-62**. **Figure 1-63** shows the compilation process.



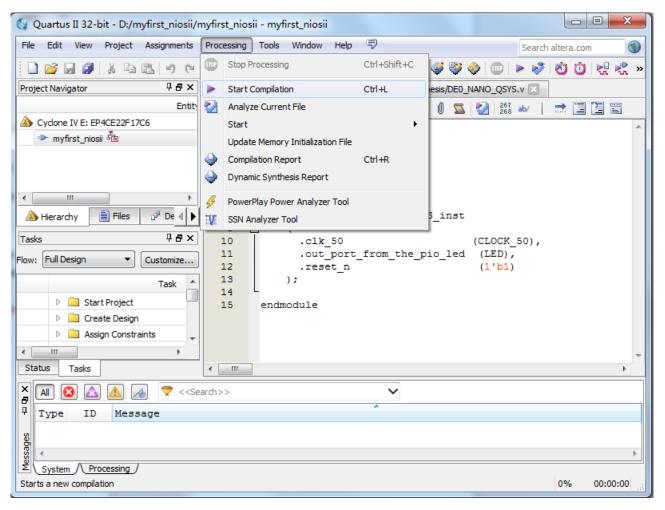


Figure 1-62 Start Compilation



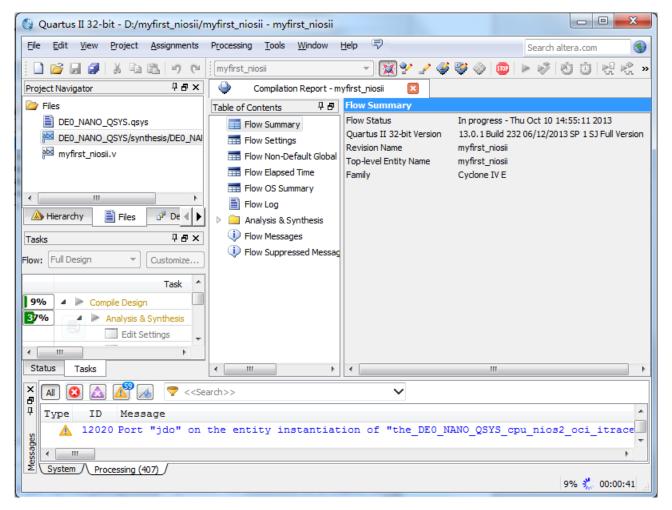


Figure 1-63 Execute Compilation

Note: In the compilation, if there is the error which shows "Error: The core supply voltage of '1.0v' is illegal for the currently selected part.", you should modify the text "set_global_assignment -name NOMINAL_CORE_SUPPLY_VOLTAGE 1.0V" to "set_global_assignment -name NOMINAL_CORE_SUPPLY_VOLTAGE 1.2V" in the myfirst_niosii.qsf of the project.

38. A window that shows successfully will appear as shown in Figure 1-64.



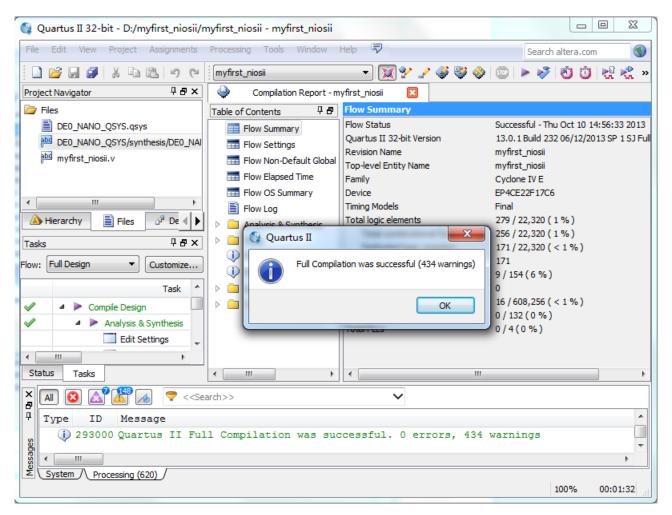


Figure 1-64 Compilation project completely

39. Choose Assignments > Pins to open pin planner as shown in **Figure 1-65**. **Figure 1-66** show blank pins.



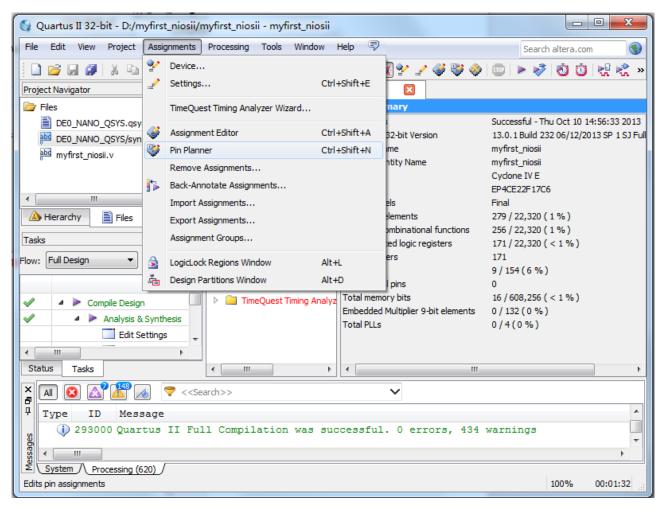


Figure 1-65 Pins menu



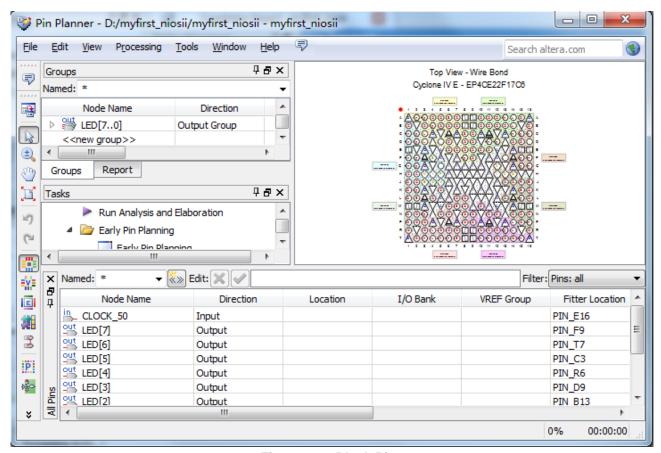


Figure 1-66 Blank Pins

40. Input Location value as shown in Figure 1-67.



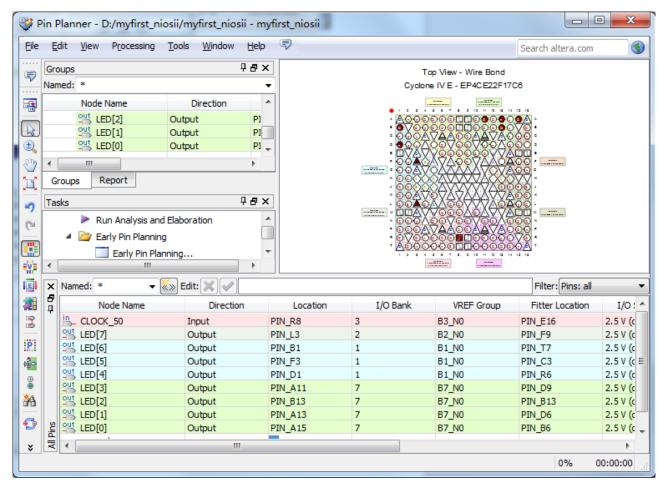


Figure 1-67 Set Pins

41. Close the **pin planner**. Restart compilation the project as shown in **Figure 1-68**.



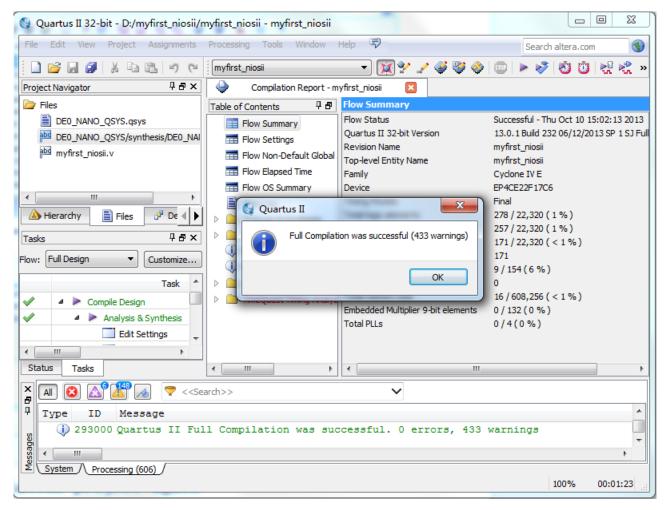


Figure 1-68 Compilation project again

1.3 Download Hardware Design to Target FPGA

This section describes how to download the configuration file to the board.

Download the FPGA configuration file (i.e. the SRAM Object File (.sof) that contains the NIOS II standard system) to the board by performing the following steps:

- 1. Connect the board to the host computer via the USB download cable.
- 2. Apply power to the board.
- 3. Start the Nios II Software Build Tools (SBT) for Eclipse.





- 4. After the welcome page appears, click Workbench.
- 5. Choose Nios II->Quartus II Programmer.
- 6. Click Auto Detect. The device on your development board should be detected automatically.
- 7. Click the top row to highlight it.
- 8. Click Change File.
- 9. Browse to the My First NiosII project directory.
- 10. Select the programming file (myfirst niosii.sof) for your board.
- 11. Click OK.
- 12. Click Hardware Setup in the top, left comer of the Quartus II programmer window. The Hardware Setup dialog box appears.
- 13. Select USB-BlasterII from the Currently selected hardware drop-down list box.

Note: If the appropriate download cable does not appear in the list, you must first install drivers for the cable. Refer to Quartus II Help for information on how to install the driver. See **Figure 1-69**.

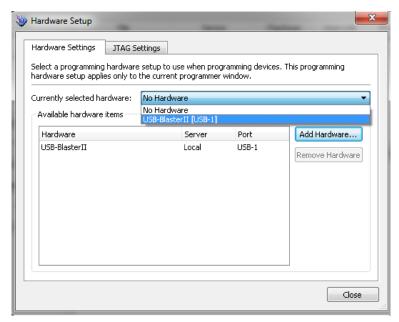


Figure 1-69 Hardware Setup Window





- 14. Click Close.
- 15. Turn on the Program/Configure option for the programming file.(See **Figure 1-70** for an example).
- 16. Click Start.

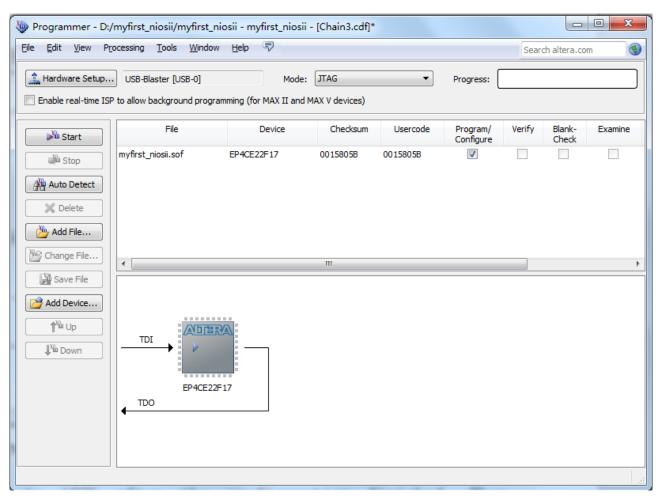


Figure 1-70 Quartus II Programmer

The Progress meter sweeps to 100% after the configuration finished. When configuration is complete, the FPGA is configured with the Nios II system, but it does not yet have a C program in memory to execute.



Chapter 2

NIOS II Softwar Build Tools for Eclipse

This Chapter covers build flow of Nios II C coded software program.

The Nios II Software Build Tools (SBT) for Eclipse is an easy-to-use graphical user interface (GUI) that automates build and makefile management. The Nios II SBT for Eclipse integrates a text editor, debugger, ,the BSP editor ,the Nios II flash programmer and the Quartus II Programmer. The included example software application templates make it easy for new software programmers to get started quickly. In this section you will use the Nios II SBT for Eclipse to compile a simple C language example software program to run on the Nios II standard system configured onto the FPGA on your development board. You will create a new software project, build it, and run it on the target hardware. You will also edit the project, re-build it, and set up a debug session.

2.1 Create the hello_world Example Project

In this section you will create a new NIOS II C/C++ application project based on an installed example. To begin, perform the following steps in the NIOS II SBT for Eclipse:

1. Return to the NIOS II Software Build Tools for Eclipse.

Note: you can close the Quartus II Programmer or leave it open in the background if you want to reload the processor system onto your development board quickly.

2. Choose File > Switch Workspace to switch workspace. See Figure 2-1 and Figure 2-2.





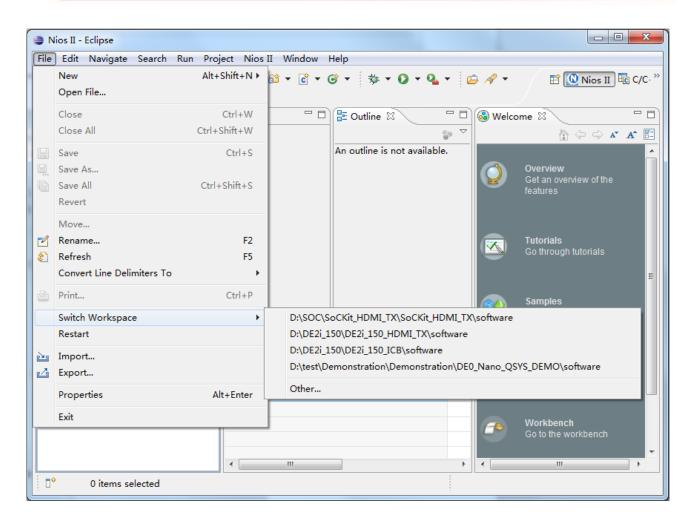


Figure 2-1 Switch Workspace (1)

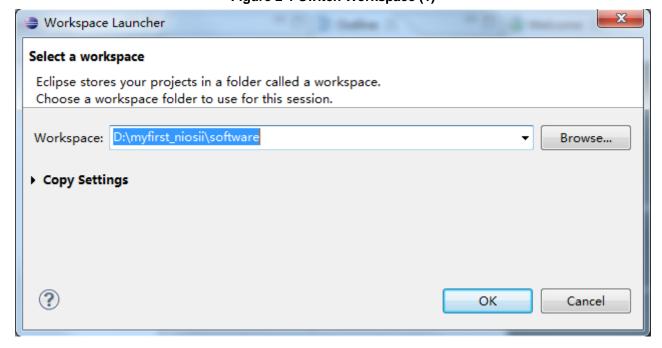






Figure 2-2 Switch Workspace (2)

- 3. Choose File->New->NIOS II Application and BSP from Template open the New Project Wizard.
- 4. In the New Project wizard, make sure the following things:
- Under Target hardware information, next to SOPC Information File name, browse to locate the <design files directory> where the previously created hardware project resides as shown in **Figure 2-3**.
- Select DE0_NANO_QSYS.sopcinfo and click Open. You return to the Nios II Application and BSP from Template wizard showing current information for the SOPC Information File name and CPU name fields.
- Select the Hello World project template.
- Give the project a name. (hello_world_0 is default name), there we rename it to hello_world_0.



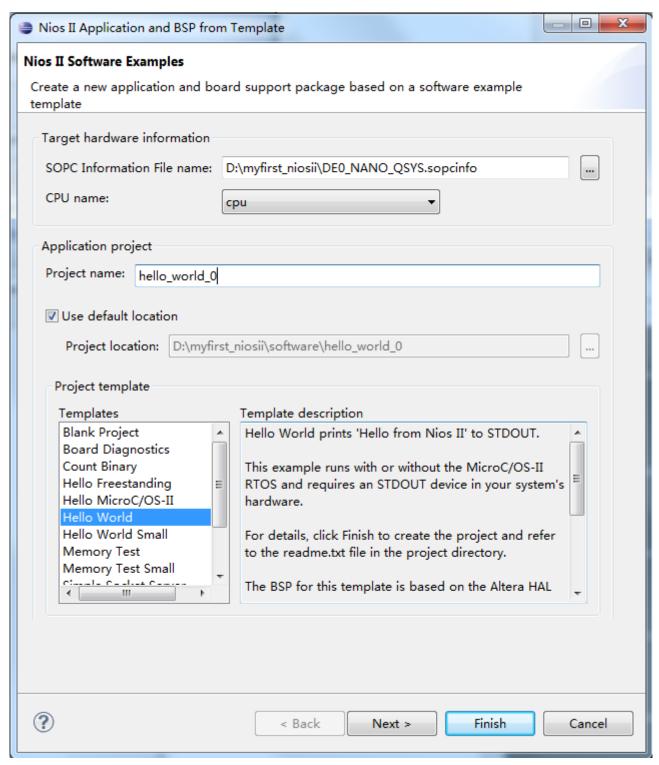


Figure 2-3 Nios II-Ecplise New Project Wizard

5. Click **Finish**. The **NIOS II SBT for Eclipse** creates the **hello_world_0** project and returns to the Nios II C/C++ project perspective. See **Figure 2-4**.





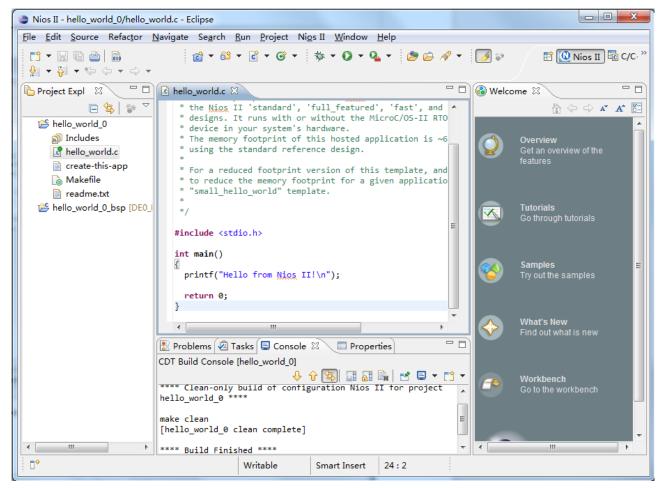


Figure 2-4 Ecplise Project Perspective for hello_world_0

When you create a new project, the NIOS II SBT for Eclipse creates two new projects in the NIOS II C/C++ Projects tab:

- hello_world_0 (hello_world_0 is default name) is your C/C++ application project. This project contains the source and header files for your application.
- ■hello_world_0 _bsp (hello_world_0_bsp is default name) is a board support package that encapsulates the details of theNios II system hardware.

Note: When you build the system library for the first time the NIOS II SBT for Eclipse automatically generates files useful for software development, including:

- Installed IP device drivers, including SOPC component device drivers for the NIOS II hardware system
- Newlib C library, which is a richly featured C library for the NIOS II processor.





- NIOS software packages which includes NIOS II hardware abstraction layer, NicheStack TCP/IP Network stack, NIOS II host file system, NIOS II read-only zip file system and Micrium's μC/OS-II real time operating system(RTOS).
- system.h, which is a header file that encapsulates your hardware system.
- alt sys init.c, which is an initialization file that initializes the devices in the system.
- Hello_world_0.elf, which is an executable and linked format file for the application located in hello world 0 folder under Debug.

2.2 Build and Run the Program

In this section you will build and run the program to execute the compiled code.

To build the program, right-click the hello_world_0 project in the Nios II C/C++ Projects tab and choose Build Project. The Build Project dialog box appears and the Eclipse begins compiling the project. When compilation completes, a message '[myfirst_niosii build complete]' will appear in the Console tab. The compilation time varies depending on your system. See **Figure 2-5** for an example.



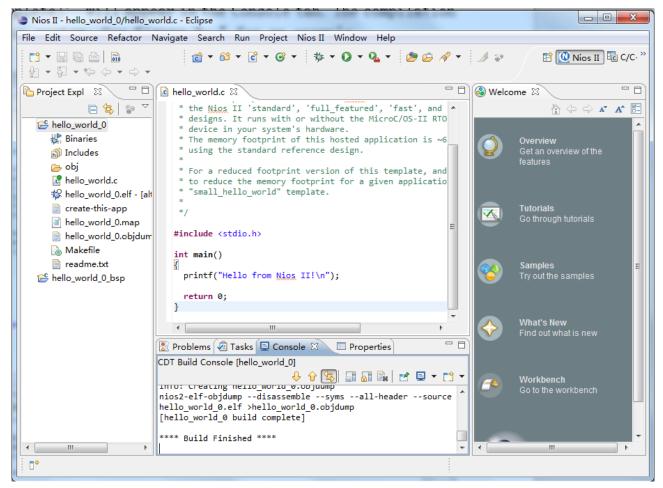


Figure 2-5 hello_world_0 Build Completed

After compilation complete, right-click the hello_world_0 project, choose Run As, and chooseNIOS II Hardware. The Eclipse begins to download the program to the target FPGA developmentboard and begins execution. When the target hardware begins executing the program, the message 'Hello from Nios II!' appears in the NIOS II SBT for Eclipse Console tab. See **Figure 2-6** for an example.



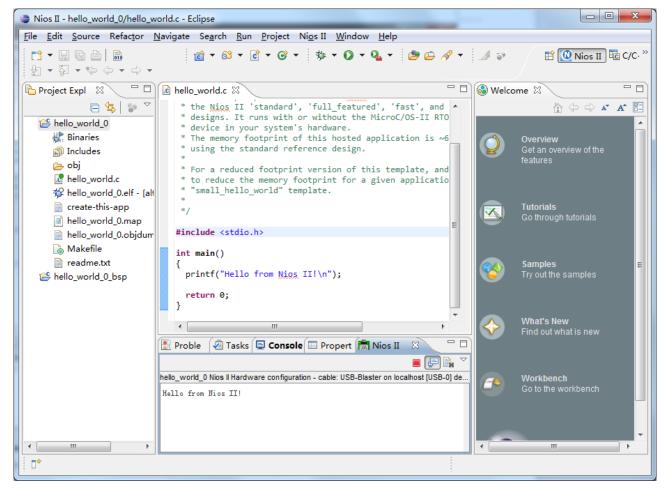


Figure 2-6 hello_world_0 Program Output

Now you have created, compiled, and run your first software program based on NIOS II. And you can perform additional operations such as configuring the system properties, editing and re-building the application, and debugging the source code.

2.3 Edit and Re-Run the Program

You can modify the hello_world.c program file in the Eclipse, build it, and re-run the program to observe your changes executing on the target board. In this section you will add code that will make LED blink.

Perform the following steps to modify and re-run the program:

1. In the hello world.c file, add the text shown in blue in the example below:

#include <stdio.h>





```
#include "system.h"
#include "altera_avalon_pio_regs.h"
int main()
{
    printf("Hello from Nios II!\n");
    int count = 0;
    int delay;
    while(1)
    {
        IOWR_ALTERA_AVALON_PIO_DATA(LED_BASE, count & 0x01);
        delay = 0;
        while(delay < 1000000)
        {
            delay++;
```

79



```
}
count++;
}
return 0;
}
```

- 2. Save the project.
- 3. Recompile the file by right-clicking hello_world_0 in the NIOS II C/C++ Projects tab and choosing Run > Run As > Nios II Hardware.

Note: You do not need to build the project manually; the NIOS II SBT for Eclipse automatically re-builds the program before downloading it to the FPGA.

4. Orient your development board so that you can observe LED blinking.

2.4 Why the LED Blinks

The Nios II system description header file, system.h, contains the software definitions, name, locations, base addresses, and settings for all of the components in the Nios II hardware system. The system.h file is located in the in the hello_world_0 _bsp directory as shown in **Figure 2-7**.



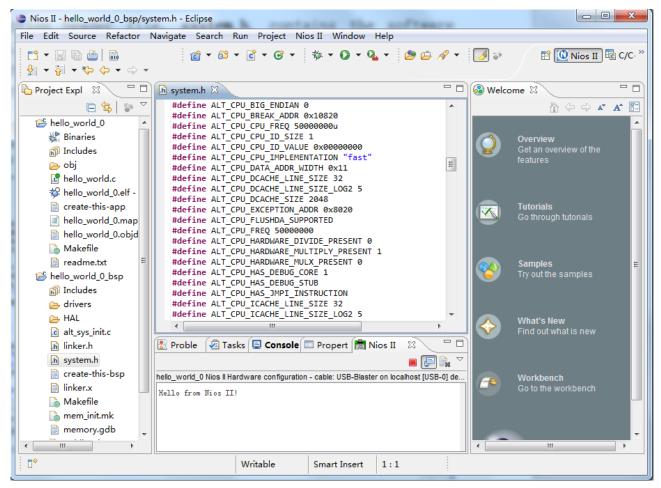


Figure 2-7 System.h Location

If you look at the system.h file for the Nios II project example used in this tutorial, you will notice the led function. This function controls the LED. The Nios II processor controls the PIO ports (and thereby the LED) by reading and writing to the register map. For the PIO, there are four registers: data, direction, interrupt mask, and edge capture. To turn the LED on and off, the application writes to the PIO data register.

The PIO core has an associated software file altera_avalon_pio_regs.h. This file defines the core's register map, providing symbolic constants to access the low-level hardware.

The altera avalon pio regs.h

file is located in altera\<version number>\ip\sopc builder ip\altera avalon pio.

When you include the altera_avalon_pio_regs.h file, several useful functions that manipulate the PIO core registers are available to your program. In particular, the function

IOWR ALTERA AVALON PIO DATA (base, data)

terasic



can write to the PIO data register, turning the LED on and off. The PIO is just one of many SOPC peripherals that you can use in a system. To learn about the PIO core and other embedded peripheral cores, refer to Quartus II Version <version> Handbook Volume 5: Embedded Peripherals.

When developing your own designs, you can use the software functions and resources that are provided with the Nios II HAL. Refer to the Nios II Software Developer's Handbook for extensive documentation on developing your own Nios II processor-based software applications.

2.5 Debugging the Application

Before you can debug a project in the NIOS II SBT for Eclipse, you need to create a debug configuration that specifies how to run the software. To set up a debug configuration, perform the following steps:

1. In the hello_world.c, double-click the front of the line which is needed to set breakpoint. See Figure 2-8.

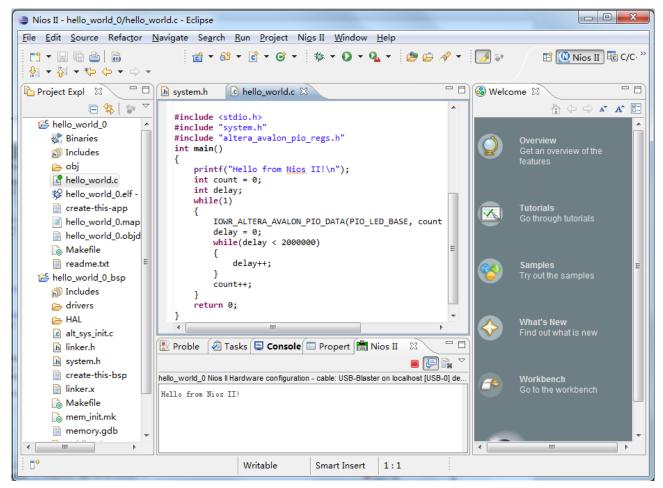
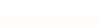


Figure 2-8 Set Breakpoint

82



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- 2. To debug your application, right-click the application (hello_world_0 by default) and choose Debug as > Nios II Hardware.
- 3. If the Confirm Perspective Switch message box appears, click Yes.
- 4. After a moment, the main () function appears in the editor. A blue arrow next to the first line of code indicates that execution stopped at that line.
- 5. Choose Run-> Resume to resume execution.

When debugging a project in the Nios II SBT for Eclipse, you can pause, stop or single step the program, set breakpoints, examine variables, and perform many other common debugging tasks.

Note: To return to the Nios II C/C++ project perspective from the debug perspective, click the two arrows >> in the top right corner of the GUI.

2.6 Configure BSP Editor

In this section you will learn how to configure some advanced options about the target memory or other things. By performing the following steps, you can charge all the available settings:

- 1. In the Nios II SBT for Eclipse, right-click hello_world_0_bsp and choose Nios II-> BSP Editor. The BSP Editor dialog box opens.
- 2. The Main page contains settings related to how the program interacts with the underlying hardware. The settings have names that correspond to the targeted NIOS II hardware.
- 3. In the Linker Script box, observe which memory has been assigned for Program memory(.text), Read-only data memory(.rodata), Read/write data memory(.rwdata), Heap memory, and Stack memory, see **Figure 2-9**. These settings determine which memory is used to store the compiled executable program when the example My_First_NiosII programs runs. You can also specify which interface you want to use for stdio, stdin, and stderr. You can also add and configure an RTOS for your application and configure build options to support C++, reduced device drivers, etc.
- 4. Choose onchip_memory2 for all the memory options in the Linker Script box. See **Figure 2-9** for an example.





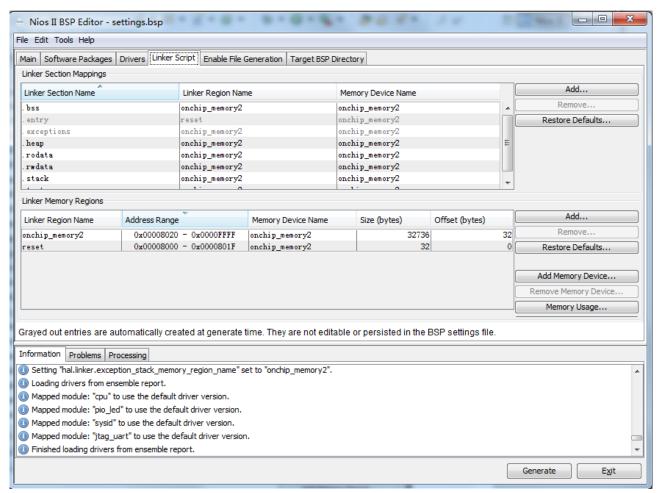


Figure 2-9 Configuring BSP

5. Click Exit to close the BSP Editor dialog box and return to the Eclipse workbench.

Note: If you make changes to the system properties or the Qsys properties or your hardware, you must rebuild your project. To rebuild, right-click the hello_world_0_BSP->Nios II->Generate BSP and then Rebuild Project.